



DEWETRON

PU[REC]

TECHNICAL REFERENCE MANUAL

**WELCOME TO
THE WORLD OF
DEWETRON!**

Congratulations on your new device! It will supply you with accurate, complete and reproducible measurement results for your decision making.

Look forward to the easy handling and the flexible and modular use of your DEWETRON product and draw upon more than 30 years of DEWETRON expertise in measurement engineering.

ISO9001



THE MEASURABLE DIFFERENCE.

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Thank you!

Thank you very much for your investment in DEWETRON's unique data acquisition systems. These are top-quality instruments which are designed to provide you years of reliable service. This guide has been prepared to help you get the most from your investment, starting from the day you take it out of the box, and extending for years into the future.

This guide includes important startup notes, as well as safety notes and information about keeping your DEWETRON system in good working condition over time.

We strongly suggest that you read this entire manual, especially the safety and care sections, as well as to avoid damaging your DEWETRON system.

What is PU[REC]?

PU[REC] stands for PURE RECORDING and is your portable and reliable data acquisition system for field tests, troubleshooting and maintenance in various application areas. The 16 available analog input channels support +/- 10 V directly and with the use of one (or more) of the nine available types of Modular Smart Interfaces (MSI) in front of the analog input, you can acquire almost any signal. The option of adding quasi-static channel expansion modules to the PU[REC] provides additional measurement inputs for voltage, current, temperature or resistance.

▼

PREFACE

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Training

DEWETRON offers training at various offices around the world several times each year. DEWETRON headquarters in Austria have a very large and professional conference and seminar center, where training classes are conducted on a regular basis starting with sensors and signal conditioning, A/D technology and software operation. For more information about training services, please visit:

<http://www.dewetron.com/services/dewetron-academy/>

Dewetron Inc. in the USA also has a dedicated training facility connected to its headquarters, located in Rhode Island. For more information about training services in the US, please visit:

<http://www.dewetron.us/service-support/system-training-usa/>

Calibration

Every instrument needs to be calibrated at regular intervals. The standard norm across nearly every industry is annual calibration. Before your DEWETRON data acquisition system is delivered, it is calibrated at our DEWETRON headquarter. Each of this system is delivered with a certificate of compliance with our published specifications. Detailed calibration reports from our calibration system are available for purchase with each order. We retain them for at least one year, so calibration reports can be purchased for up to one year after your system was delivered.

Support

DEWETRON has a team of people ready to assist you if you have any questions or any technical difficulties regarding the system. For any support please contact your local distributor first or DEWETRON directly.

For Asia and Europe, please contact:

DEWETRON GmbH
Parkring 4
8074 Grambach
AUSTRIA
Tel.: +43 316 3070
Fax: +43 316 307090
Email: support@dewetron.com
Web: <http://www.dewetron.com>

The telephone hotline is available
Monday to Friday between
08:00 and 17:00 CET (GMT +1:00)

For the Americas, please contact:

DEWETRON, Inc. (HQ USA)
2850 South County Trail, Unit 1
East Greenwich, RI 02818
U.S.A.
Tel.: +1 401 284 3750
Toll-free: +1 866 598 3393
Fax: +1 401 284 3755
Email: us.support@dewetron.com
Web: <http://www.dewetron.us>

The telephone hotline is available
Monday to Friday between
08:00 and 4:30 EST

Service/Repair Policy

We are very sorry that your DEWETRON system is not operating properly. Our team is here to ensure that your DEWETRON product is returned to peak performance as quickly as possible.

Please help us to help you by following the RMA policy.

Some problems can be solved remotely by our support team. To facilitate a quicker resolution to the problem and save unnecessary shipping costs, we ask you to first have your problem investigated by our technical support before sending your product. Contact details for our support can be found on our [website](#). Please describe the error accurately and with as much detail as possible. This helps expedite the repair process.

If a repair is necessary, please complete our [online RMA form](#). You will then receive an RMA (Return Material Authorization) number and detailed instructions that identify where to ship the damaged product.

Please note: Products arriving at our repair department without RMA require follow-up calls and investigation, which lead to longer turnaround. Only the team of DEWETRON is allowed to perform any kinds of repairs to your system to assure a safe and proper operation in future.



Any spare parts (screws, backplanes, cables,...) must be obtained from DEWETRON only.



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Warranty Information

A copy of the specific warranty terms applicable to your DEWETRON product and replacement parts can be obtained from your local sales and service office.

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DEWETRON GmbH
Parkring 4
A-8074 Grambach / Austria

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Safety conventions



Observe precautions for handling electrostatic sensitive devices!



This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash. When this symbol is marked on the product, refer to the technical reference manual.



Indicates hazardous voltages.



Indicates the chassis terminal

WARNING *Calls attention to a procedure, practice, or condition that could cause bodily injury or death.*

CAUTION *Calls attention to a procedure, practice, or condition that could possibly cause damage to equipment or permanent loss of data.*

WARNINGS

The following general safety precautions must be observed during all phases of operation, service, and repair of this product. Failure to comply with these precautions or with specific warnings elsewhere in this manual violates safety standards of design, manufacture, and intended use of the product. DEWETRON GmbH assumes no liability for the customer's failure to comply with these requirements.

SAFETY INSTRUCTIONS

Your safety is our primary concern! Please be safe!



General safety and hazard warnings for all DEWETRON systems

- > Use this system under the terms of the specifications only to avoid any possible danger. If the unit is used in a manner not specified by the manufacturer the protection can be impaired!
- > This product is intended for use in industrial locations. As a result, this product may cause interference if used in residential areas. Such use must be avoided unless the user takes special measures to reduce electromagnetic emissions to prevent interferences to the reception of radio and television broadcasts.
- > Maintenance will be executed by qualified staff only.
- > During the use of the system, it might be possible to access another parts of a more comprehensive system. Please read and follow the safety instructions provided in the manuals of all other components regarding warning and security advices for using the system.
- > With this product, only use the power cable delivered or defined for the host country.
- > DO NOT connect or disconnect sensors, probes or test leads, as these parts are connected to a voltage supply unit.
- > The system is grounded via a protective conductor in the power supply cord. To avoid electric shocks, the protective conductor has to be connected with the ground of the power network. Before connecting the input or output connectors of the system, make sure that there is a proper grounding to guarantee potential free usage. For countries, in which there is no proper grounding, please refer to your local legally safety regulations for safety use.

DC systems: Every DC system has a grounding connected to the chassis (yellow/green safety banana plug).

- > Please note the characteristics and indicators on the system to avoid fire or electric shocks. Before connecting the system, please carefully read the corresponding specifications in the product manual.
- > The inputs are not, unless otherwise noted (CATx identification), for connecting to the main circuits of category II, III and IV. The measurement category can be adjusted depending on module configuration.
- > The power cord separates the system from the power supply. Do not block the power cord, since it has to be accessible for the users.
- > Supply overvoltage category is II.
- > DO NOT use the system if equipment covers or shields are removed.
- > If you assume the system is damaged, get it examined by authorised personnel only.
- > Any use in wet rooms, outdoors or in adverse environmental condition is not allowed!
Adverse environmental conditions are:
 - > Moisture or high humidity
 - > Dust, flammable gases, fumes or dissolver
 - > Thunderstorm or thunderstorm conditions (except assembly PNA)
 - > Electrostatic fields, et cetera.
- > Any direct voltage output is protected with a fuse against short cut and reverse-polarity, but is NOT galvanically isolated (except it is explicit marked on the system).
- > The system must be connected and operated to an earthed wall socket at the AC mains power supply only (except for DC systems).
- > Any other use than described above may damage your system and is attended with dangers like shortcut, fire or electric shocks.

SAFETY INSTRUCTIONS

- > The whole system must not be changed, rebuilt or opened (except for changing TRION™ modules).
 - > If you assume a more riskless use is not provided anymore, the system has to be rendered inoperative and should be protected against inadvertent operation. It is assumed that a more riskless operation is not possible anymore, if
 - > the system is damaged obviously or causes strange noises.
 - > the system does not work anymore.
 - > the system has been exposed to long storage in adverse environmental.
 - > the system has been exposed to heavy shipment strain.
 - > DO NOT touch any exposed connectors or components if they are live wired. The use of metal bare wires is not allowed. There is a risk of short cut and fire hazard!
 - > Warranty void if damages caused by disregarding this manual. For consequential damages NO liability will be assumed!
 - > Warranty void if damages to property or persons caused by improper use or disregarding the safety instructions.
 - > Unauthorized changing or rebuilding the system is prohibited due to safety and permission reasons (CE). Exception: changing DAQP/PAD/HSI/TRION™/TRION3™ modules.
 - > The assembly of the system is equivalent to protection class I. For power supply, only the correct power socket of the public power supply must be used, except the system is DC powered.
 - > Be careful with voltages $>25 V_{AC}$ or $>35 V_{DC}$! These voltages are already high enough in order to get a perilous electric shock by touching the wiring.
 - > Unless otherwise stated, maximum input voltage for measuring cards are $70 V_{DC}$ and $46.7 V_{PEAK}$.
 - > The product heats during operation. Make sure there is adequate ventilation. Ventilation slots must not covered!
 - > Only fuses of the specified type and nominal current may be used. The use of patched fuses is prohibited.
 - > Prevent using metal bare wires! Risk of short cut and fire hazard!
 - > DO NOT use the system before, during or shortly after a thunderstorm (risk of lightning and high energy overvoltage). An advanced range of application under certain conditions is allowed with therefore designed products only. For details please refer to the specifications.
 - > Make sure that your hands, shoes, clothes, the floor, the system or measuring leads, integrated curcuits and so on, are dry.
 - > DO NOT use the system in rooms with flammable gases, fumes or dust or in adverse environmental conditions.
 - > Avoid operation in the immediate vicinity of:
 - > high magnetic or electromagnetic fields
 - > transmitting antennas or high-frequency generators
- For exact values please refere to enclosed specifications.
- > Use measurement leads or measurement accessories aligned to the specification of the system only. Fire hazard in case of overload!
 - > Do not switch on the system after transporting it from a cold into a warm room and vice versa. The thereby created condensation may damage your system. Acclimatise the system unpowered to room temperature.
 - > Do not disassemble the system! There is a high risk of getting a perilous electric shock. Capacitors still might charged, even the system has been removed from the power supply.

SAFETY INSTRUCTIONS

- > Direct exposure of any DEWETRON product to strong sunlight or other heat radiation shall be prevented, as this could excessively heat up the product and lead to permanent damage of the product.
- > The electrical installations and equipments in industrial facilities must be observed by the security regulations and insurance institutions.
- > The use of the measuring system in schools and other training facilities must be observed by skilled personnel.
- > The measuring systems are not designed for use at humans and animals.
- > Please contact a professional if you have doubts about the method of operation, safety or the connection of the system.
- > Please be careful with the product. Shocks, hits and dropping it from already lower level may damage your system. For exact values please refer to enclosed specifications.
- > Please also consider the detailed technical reference manual as well as the security advices of the connected systems.

This product has left the factory in safety-related flawless and proper condition.

In order to maintain this condition and guarantee safety use, the user has to consider the security advices and warnings in this manual.

EN 61326-3-1:2008

IEC 61326-1 applies to this part of IEC 61326 but is limited to systems and equipment for industrial applications intended to perform safety functions as defined in IEC 61508 with SIL 1-3.

The electromagnetic environments encompassed by this product family standard are industrial, both indoor and outdoor, as described for industrial locations in IEC 61000-6-2 or defined in 3.7 of IEC 61326-1. Equipment and systems intended for use in other electromagnetic environments, for example, in the process industry or in environments with potentially explosive atmospheres, are excluded from the scope of this product family standard, IEC 61326-3-1.

Devices and systems according to IEC 61508 or IEC 61511 which are considered as “operationally well-tried”, are excluded from the scope of IEC 61326-3-1.

Fire-alarm and safety-alarm systems, intended for protection of buildings, are excluded from the scope of IEC 61326-3-1.

Maintenance

The information in this section is designed for use by qualified service personal.

Service interval:

Clean dust from the chassis exterior/interior and exchange filter foam based on the operating environment.

Cleaning:

Clean surface of the chassis with dry lintfree cloth.

Use a dry velocity stream of air to clean the chassis interior.



- > Disconnect all cables before servicing the unit!
- > Many components within the chassis are sensitive to static discharge damage. Always wear a ground wrist strap and service the unit only in static-free environment.
- > Do not use harsh chemical cleaning agents!

GENERAL INFORMATION

CAUTION

- > The system BIOS is protected by password. Any change in the BIOS may cause a system crash. When the system is booting, do not press ESC-button on keyboard. This may clear the BIOS settings and cause system faults.
- > Any change in the file structure as deleting or adding files or directories might cause a system crash.
- > Before installing software updates contact DEWETRON or your local distributor. Use only software packages which are released by DEWETRON. Further informations are also available in the internet (<http://www.dewetron.com>).
- > After power off the system wait at least 10 seconds before switching the system on again. Otherwise the system may not boot correct. This prolongs also the life of all system components.
- > If the AC plug of the power supply unit is disconnected and then reconnected, it may not be possible to restart the PU[REC]. In this case, the system must be disconnected from the power supply for 1 minute before it can be restarted.

Windows updates and antivirus/security software

Before installing Windows software updates consult with DEWETRON for compatibility guidance. Please also keep in mind that the use of any antivirus or other security software may slow down your system and may cause data loss.

Problematic network stacks

Often intrusive IT software or network processes can interfere with the primary function of the DEWETRON system: to record data. Therefore we recommend strongly against the installation of IT/MIS software and running their processes on any DEWETRON data acquisition system, and cannot guarantee the performance of our systems if they are so configured.



Environmental Considerations

Information about the environmental impact of the product.

Product End-of-Life Handling

Observe the following guidelines when recycling a DEWETRON system:

System and Components Recycling

Production of these components required the extraction and use of natural resources. The substances contained in the system could be harmful to your health and to the environment if the system is improperly handled at it's end of life! Please recycle this product in an appropriate way to avoid an unnecessary pollution of the environment and to keep natural resources.

This symbol indicates that this system complies with the European Union's requirements according to Directive 2012/19/EU on waste electrical and electronic equipment (WEEE). Please find further information about recycling on the DEWETRON website www.dewetron.com

Restriction of Hazardous Substances

This product has been classified as Monitoring and Control equipment, and is outside the scope of the 2011/65/EU RoHS Directive. This product is known to contain lead.

PU[REC] - portable data recorder

- > 16 analog input channels
(expandable to any signal input via Modular Smart Interfaces)
- > Quasi-static channel expansion via EPAD2
- > Available with 50 kS/s or 200 kS/s (optional) sampling rate
- > 15.6" multi-touch display
- > Rugged and portable housing for easy transportation












System specifications

| PU[REC] | |
|---|---|
| Configuration | |
| Sampling rate / resolution | PUREC-50: 50 kS/s per channel 16-bit PUREC-200: 50 kS/s to 200 kS/s 18-bit 100 S/s to 50 kS/s 24-bit |
| Digital input | 2x counter shared with 8x digital inputs; 4x digital outputs |
| CAN bus | 1x highspeed CAN 2.0 (ordering option PUREC-OPT-CAN) |
| Quasi-static channel expansion | EPAD2 interface connector |
| Expansion | SYNC-BUS (requires ordering option OXY-OPT-NET) |
| Main system | |
| Display | 15.6" multi-touch TFT (full HD 1920 x 1080) |
| Additional Connectors | 2x Display Port; 1x HDMI; Audio interface (3x 3.5mm connectors) 4x USB 3.0; 2x Gbit LAN; |
| Operating system | Microsoft Windows 10 64-bit; (optional Linux OS) |
| Data Storage | 1 TB SSD in a removeable drive bay (870 GB useable for data storing) up to 7 days of recording all channels at 50 kS/s or 300 days at 1 kS/s |
| MTBF | 27800 hours |
| Noise emission | system idle 38 dBA CPU max. heat; max. fan: 45 dBA |
| Dimensions (W x D x H) | 463 x 129 x 318 mm (18.2 x 5.1 x 12.5 in.) |
| Weight | 7.3 kg (16.1 lb.) |
| Power supply | |
| Rated input voltage | 100 to 240 V _{AC} (max 90 to 264 V _{AC}), active PFC |
| Input frequency | 47 to 63 Hz |
| Maximal input current | 2 A (230 V _{AC}) / 4 A (115 V _{AC}) |
| Inrush current | 80 A (264 V _{AC}) |
| Power consumption | max. 300 W; typical 65W (fully equipped with MSI, recording data) |
| Environmental specifications | |
| Operating temperature | 0 to +50 °C, down to -20 °C with prewarmed unit |
| Storage temperature | -20 to +70 °C |
| Humidity | 10 to 80 % non cond., 5 to 95 % rel. humidity |
| Max. altitude | 2000 m (6561 ft) |
| Sine vibration (EN 60068-2-6:2008) | Acceleration: 20 m/s ² Frequency range: 10 Hz - 150 Hz Sweep: 1 oct/min 20 cycles |
| Shock (EN 60028-2-27:2009) | Acceleration: 15 g Duration: 11 ms Pulse form half sine 3 pumps/direction 6 directions |
| Random vibration (EN IEC 60721-3-2:2018) | Class 2M4 Spectral acceleration density: 1 m ² /s ³ Frequency range: 10 Hz-200 Hz Duration: 30 min/direction |

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MAIN SYSTEM

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| Input types | | | | | |
|------------------------------|--|-------------------------|---|--------------------------------|--------------------------------|
| | Input | Sensor excitation | Bandwidth <small>(max.) consider limit of PU[REC]</small> | Accuracy <small>(typ.)</small> | Sensor connection |
| Direct voltage input | ±10 V; ±5 V | ±5 V; 12 V | DC to 70 kHz | 0.02 % | D-SUB-9 |
| MSI2-250R-20mA ¹⁾ |  4 to 20 mA sensors | n/a | DC to 70 kHz | ±0.1 % | Miniature spring terminals |
| MSI2-STG ¹⁾ |  Bridge-type sensors full-bridge, half-bridge, quarter-bridge 120 Ω and 350 Ω | 5 V and 10 V | 60 kHz | ±0.1 % | Miniature spring terminals |
| MSI2-LVDT ¹⁾ |  LVDT and RVDT sensors, 5- or 6-wire connection | 3 V at 2.5, 5 or 18 kHz | 1 kHz | ±0.1 % | Soldering pads |
| MSI-BR-ACC ¹⁾ |  IEPE® sensors, typ. accelerometer, microphone | 4 mA | 1.4 Hz to 70 kHz | ±0.2 % | BNC |
| MSI2-CH-x ¹⁾ |  Charge type sensors up to 100 000 pC | n/a | 0.08 Hz to 70 kHz | ±0.5 % | BNC |
| MSI2-TH-x ¹⁾ |  Thermocouple sensors standard models for type K, J, T, others on request | n/a | DC to 70 kHz | ±1 °C | Mini TC socket |
| MSI-BR-V-200 ¹⁾ |  Voltage up to 200 V | n/a | DC to 60 kHz | ±0.1 % | BNC |
| MSI2-V-600 ¹⁾ |  Voltage up to 600 V | n/a | DC to 60 kHz | ±0.1 % | Banana sockets |
| MSI-BR-RTD ¹⁾ |  RTD sensors Pt100, Pt200, Pt500, Pt1000, Pt2000; 2-, 3- and 4-wire connection | 1.25 mA | DC to 10 kHz | ±0.1 % | Binder 712 series 5-pin socket |

¹⁾ MSIs are automatically detected

| Direct voltage input specification | | | | |
|---|---|--------------------------------|--|--------------------|
| Input connector | 16x 9-pin female D-SUB | | | |
| Input ranges | ±10 V; ±5V | | | |
| Sensor excitation | ±5 V | Accuracy: | ±0.2 %; balanced around GND; remote sense support max. 40 mA per channel | |
| | 12V | Protection: | Continuous short to GND; short circuit limit is 70 mA | |
| | | Accuracy: | ±5 %; max. 1 A in total for all channels, including EPAD2 supply | |
| | | Protection: | Self resetting fuse." | |
| Input noise | 0 to 10 Hz: | 10 μV _{pp} | | |
| | full bandwidth: | 1.35 mV _{pp} | | |
| Input impedance | 1 MΩ single ended, 2 MΩ differential | | | |
| Input bias current | <25 pA | | | |
| Input coupling | DC | | | |
| Accuracy ¹⁾ | Voltage | DC to 1 kHz | ±0.02 % of reading ± 0.01 % of range ±20 μV | |
| | | >1 kHz to 5 kHz | ±0.5 % of reading ± 0.01 % of range ±20 μV | |
| | | >5 kHz to 10 kHz ²⁾ | ±1 % of reading ± 0.01 % of range ±20 μV | |
| Gain drift | typical 10 ppm/°C max. 20 ppm/°C | | | |
| Offset drift | typical 0.3 μV/°C + 10 ppm of range/°C, max 15 μV/°C + 20 ppm of range/°C | | | |
| Typical Signal-to-noise ratio, Spurious-free SNR, Effective number of Bits, VPP ²⁾ | 10 V range | | | |
| | | SNR | SFDR ³⁾ | ENOB ⁴⁾ |
| | Sample rate | [dB] | [dB] | [Bit] |
| | 0.1 kS/s | 127 | 130 | 20.8 |
| | 1 kS/s | 118 | 130 | 19.3 |
| | 10 kS/s | 109 | 130 | 17.8 |
| | 20 kS/s | 106 | 130 | 17.3 |
| | 50 kS/s ²⁾ | 102 ²⁾ | 130 ²⁾ | 16.7 |
| | 100 kS/s ²⁾ | 99 ²⁾ | 130 ²⁾ | 16.2 |
| | 200 kS/s ²⁾ | 96 ²⁾ | 125 ²⁾ | 15.7 |
| Linearity | <20 ppm | | | |
| Input configuration | differential | | | |
| Typical THD | -95 dB | | | |

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| | | |
|--|--|--|
| Typical CMRR in differential mode | | 100 dB @ 50 Hz; >70 dB @ 1 kHz |
| Low pass Filter (-3 dB, IIR) | | 1 Hz to 40 % of sample rate freely programmable or OFF |
| | Characteristic Filter order | Bessel or Butterworth 2nd, 4th, 6th, 8th |
| Analog antialiasing filter | | 3 rd order Butterworth |
| Bandwidth (-3 dB, deactivated IIR filter) | | 70 kHz 3 rd order Butterworth filter |
| Crosstalk fin 1 kHz [10 kHz] | | >108 dB |
| Channel to channel phase mismatch | | typically <30 nsec when using the same input range |
| Common mode voltage | | $\pm 12.5 V_{DC}$ |
| Overvoltage protection (IN+, IN-, Sense) | | $\pm 50 V_{DC}$ |
| Digital IN specification | | |
| Digital Input | | 8 CMOS/TTL compatible digital inputs; weak pullup via 100 k Ω |
| Overvoltage protection | | $\pm 30 V$, $50 V_{PK}$ (for 100 ms) |
| Counter | | 2 counter channels; TTL input; shared with digital inputs |
| Counter modes | Event counting Waveform timing Sensor modes | Basic event counting, gated counting, up/down counting and encoder mode (X1, X2 and X4) Period, frequency, pulse width duty cycle and edge separation Encoder (angle and linear) |
| Digital OUT specification | | |
| Digital output | | 4 DO; TTL |
| Output indication | | LED (green = high; off = low) |
| Maximum current | | 25 mA continuously |
| Power-on default | | Low |
| Interfaces | | |
| CAN bus | CAN specification CAN Physical Layer Bus pin fault protection Termination | 1 CAN Bus; not isolated CAN 2.0B High Speed $\pm 36 V$ Programmable: High impedance or 120 Ω |

¹⁾ 1 year accuracy 25 °C ± 5 °C
²⁾ LP Filter in auto mode
³⁾ SFDR excluding harmonics
⁴⁾ ENOB calculated from SNR

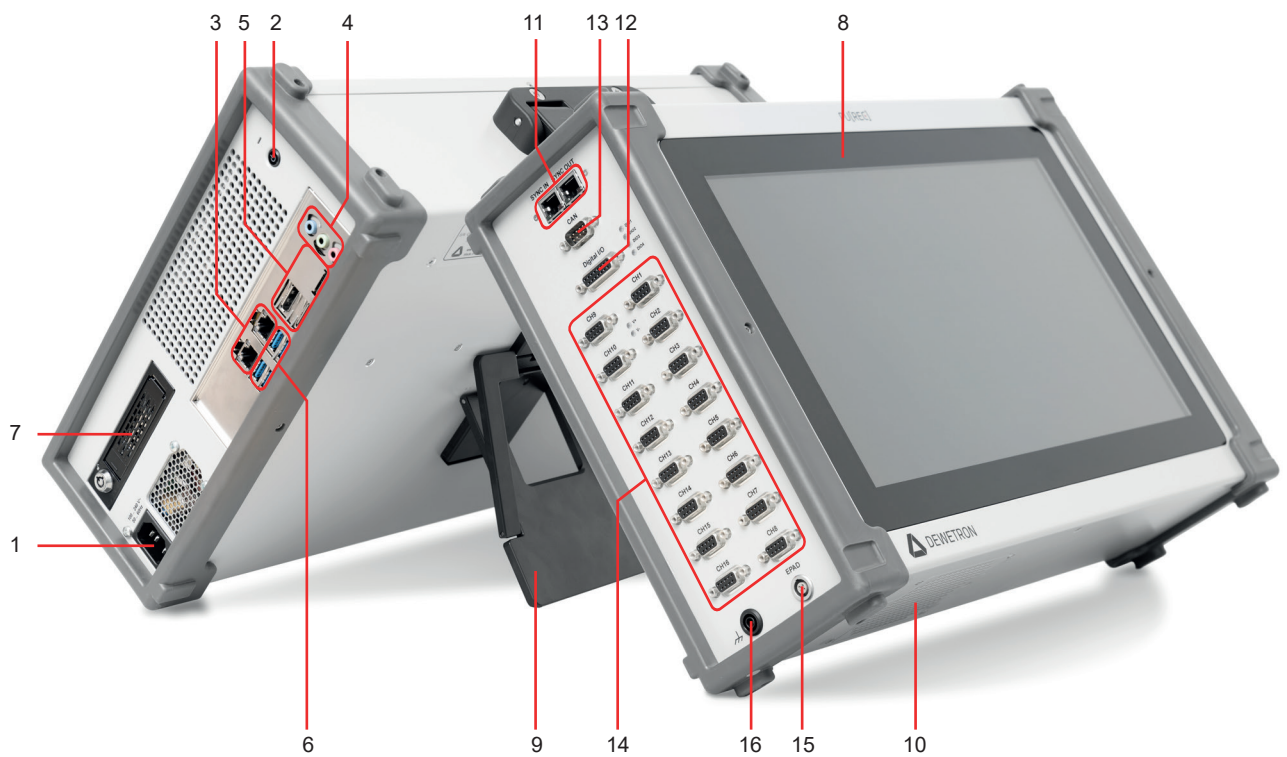
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MAIN SYSTEM

Notes

PU[REC] at a glance

- | | | | |
|---|------------------------------|----|----------------------------------|
| 1 | Power supply input connector | 9 | Fold-out stand |
| 2 | Power on/off push button | 10 | Intake vent and filter pad |
| 3 | Dual LAN GBit connectors | 11 | SYNC-BUS |
| 4 | Audio interface | 12 | Digital Input & Output connector |
| 5 | 2x Display port, 1x HDMI | 13 | CAN connector (optional) |
| 6 | 4x USB 3.1 GEN2 | 14 | 16x analog input |
| 7 | SSD drive bay | 15 | EPAD2 interface connector |
| 8 | 15.6" multi-touch display | 16 | Chassis terminal |



Note: The amount and location of the connectors might vary from system to system and depends on system configuration

MAIN SYSTEM

1 Power supply input connector



VOLTAGE **V** 100 to 240 V_{AC} (max. 90 to 264 V_{AC})

FREQUENCY **Hz** 47 to 63 Hz

POWER **P** 300 W

2 Power on/off push button

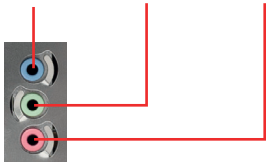
The power on/off push button at the front of the system is used to switch on the system.

3 2x GBit Ethernet connector

The PU[REC] supports 10/100/1000 Dual LAN with standard RJ45 connectors.

4 Audio I/O interface

Line In / Line Out / Microphone.



5 2x Display port, 1x HDMI

The PU[REC] supports a maximum of 3 screens at the same time.

6 4x USB3.1 interface connectors

The USB3.1 Gen 2 interface connectors meet standard USB pin assignment.



7 SSD drive bay



Ejecting SSD:

- 1 Shut down the device and wait until it is switched off (green LED goes off)
- 2 If the drive is locked unlock it with the supplied keys
- 3 Press the drive tray ejection button
- 4 Push the cover of the tray to the side until it is detached from the bay
- 5 Pull out the tray with the drive

8 15.6" multi-touch display

The PU[REC] is equipped with a bright 15.6" multi-touch panel (1920 x 1080 px) to control the instrument. Familiar gestures such as pinch and zoom are fully implemented within the operating system and will be described in chapter '[Operating with the touchscreen](#)'.

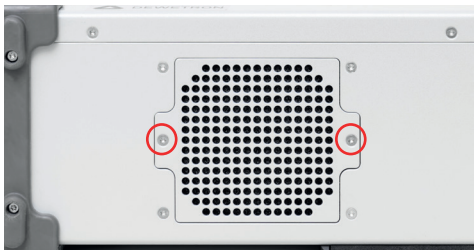
9 Fold-out stand

The fold-out stand on the PU[REC] is designed to guarantee a secure stand and to facilitate touchscreen operations.



10 Intake vent with filter pad

The intake vent with the filter pad is located at the bottom of the instrument and fixed with two Torx M3x6 screws.



Further information on how to clean the filter pad please refer to chapter '[Maintenance](#)'.

11 SYNC-BUS

The SYNC-BUS consists of two RJ45 connectors, allowing to easily synchronize two or more PU[REC]s with software option OXY-OPT-NET.



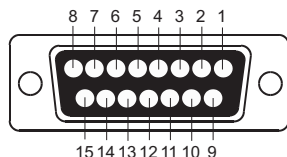
Further information on how to synchronize two or more PU[REC]s please refer to chapter '[Synchronization options](#)'.

MAIN SYSTEM

12 Digital input & output connector (Digital I/O)



15-pin D-SUB connector (female)



Schematic

| | | | |
|--------|---------------------|---------|--------------------|
| Pin 1: | DI1 / CNT1 Input_A | Pin 9: | DI2 / CNT1 Input_B |
| Pin 2: | DI3 / CNT1 Input_Z | Pin 10: | DI4 / CNT2 Input_A |
| Pin 3: | DI5 / CNT2 Input_B | Pin 11: | DI6 / CNT2 Input_Z |
| Pin 4: | DI7 | Pin 12: | DI8 |
| Pin 5: | DO1 | Pin 13: | DO2 |
| Pin 6: | DO3 | Pin 14: | DO4 |
| Pin 7: | GND | Pin 15: | NC |
| Pin 8: | +12 V (max. 600 mA) | | |

NC .. not connected

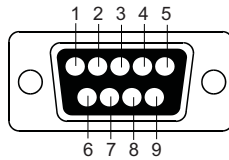
LED for digital output

green: Output high
OFF: Output low

13 CAN interface connector (optional)



9-pin D-SUB connector (male)



Schematic

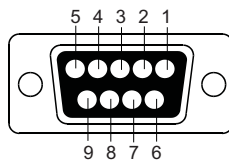
| | |
|--------|-------------------------|
| Pin 1: | +5 V out (max. 500 mA) |
| Pin 2: | CAN Low (isolated) |
| Pin 3: | GNDx CAN (isolated) |
| Pin 4: | NC |
| Pin 5: | NC |
| Pin 6: | GND Power |
| Pin 7: | CANx High (isolated) |
| Pin 8: | NC |
| Pin 9: | +12 V out (max. 600 mA) |

NC .. not connected

14 16x analog input



9-pin D-SUB connector (female)



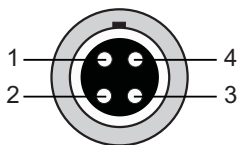
Schematic

| | |
|--------|-------------|
| Pin 1: | EXC+ (+5 V) |
| Pin 2: | IN+ |
| Pin 3: | Sense- |
| Pin 4: | GND |
| Pin 5: | 12 V |
| Pin 6: | Sense+ |
| Pin 7: | IN- |
| Pin 8: | EXC (-5 V) |
| Pin 9: | TEDS |

Housing connected to Chassis GND

15 EPAD2 connector

To connect EPAD2 modules to the instrument.



Lemo EGG.1B.304

Pin assignment

| | |
|----|----------|
| 1: | RS-485 A |
| 2: | RS-485 B |
| 3: | +12 V |
| 4: | GND |

Shield is connected on housing

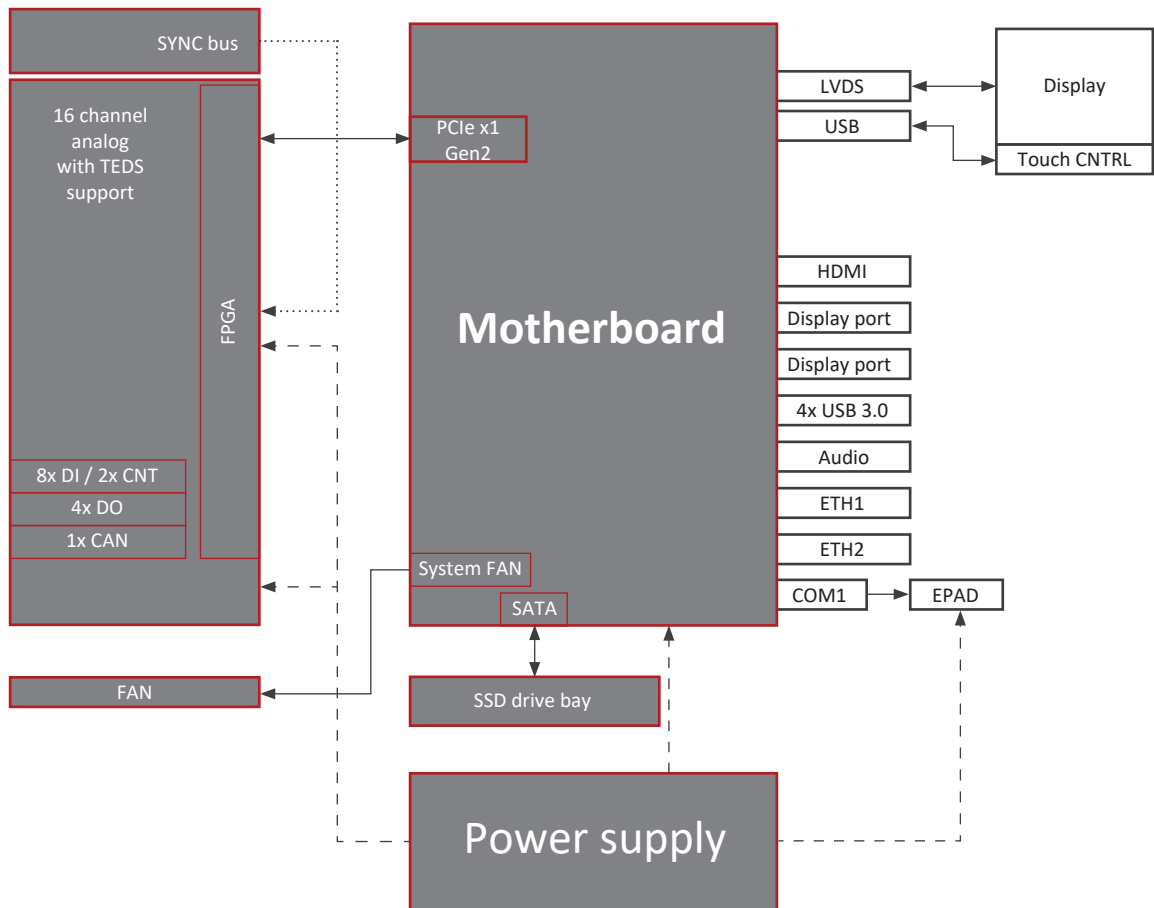
Mating connector:

LEMO FGG.1B.304.CLAD52Z (for cable diameter 4.1 to 5.0 mm)
LEMO FGG.1B.304.CLAD62Z (for cable diameter 5.1 to 6.0 mm)

16 Chassis GND

For some kind of measurements, it's necessary to provide the system with an additional ground connection.

Block diagram



▼

MAIN SYSTEM

Notes

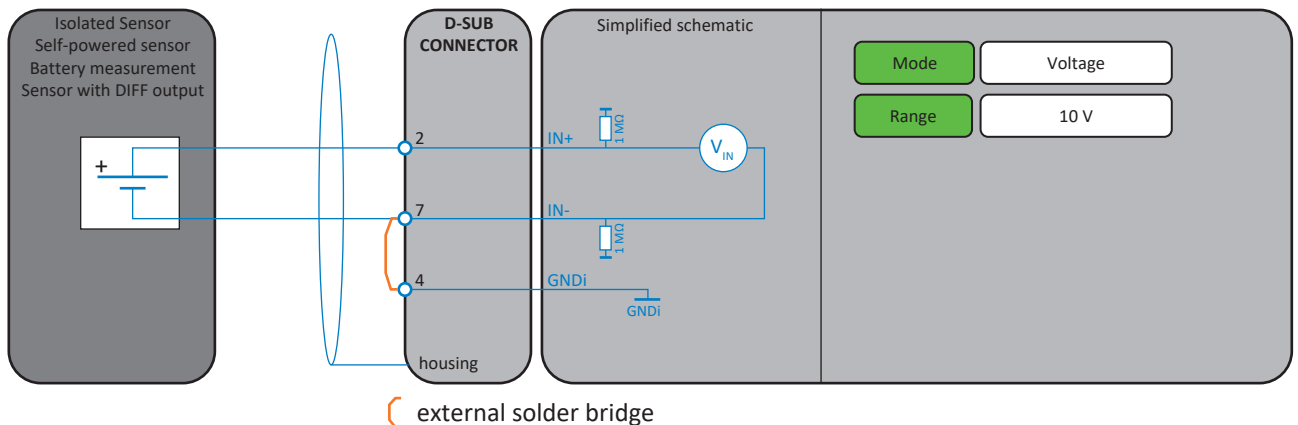
Signal connection

Direct voltage input

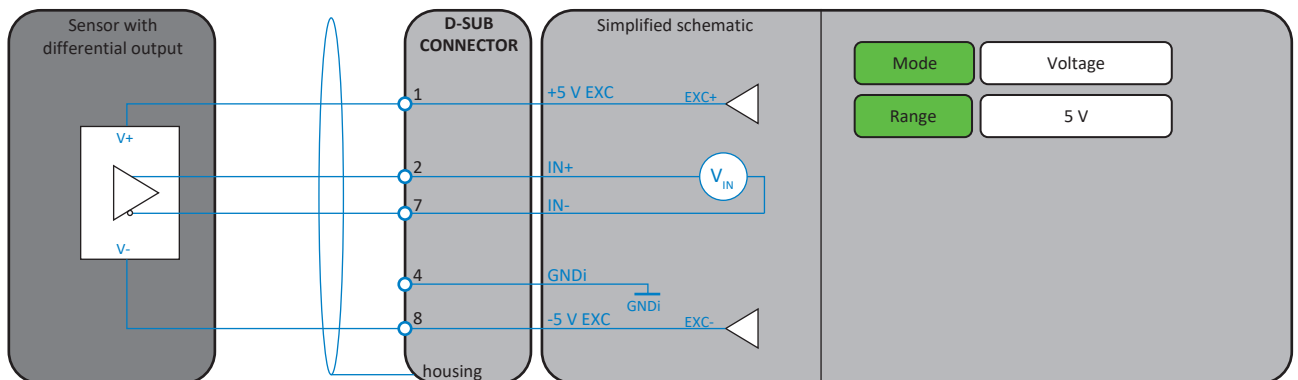


CAUTION: Input is not isolated. Do not exceed ± 12.5 V common mode voltage.

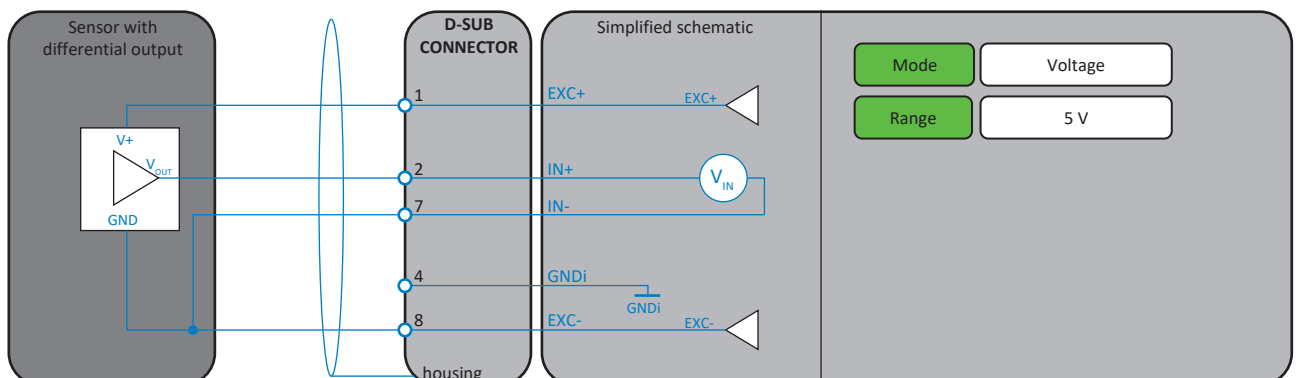
Voltage measurement



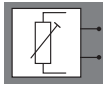
Differential output sensor powered by the instrument



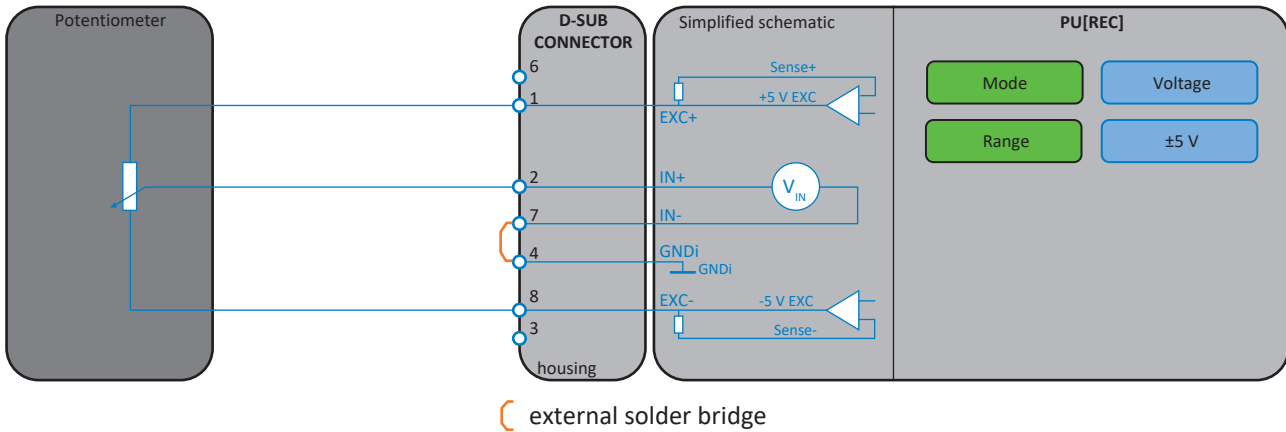
Single-ended sensor powered by the instrument



MAIN SYSTEM



Potentiometric sensor



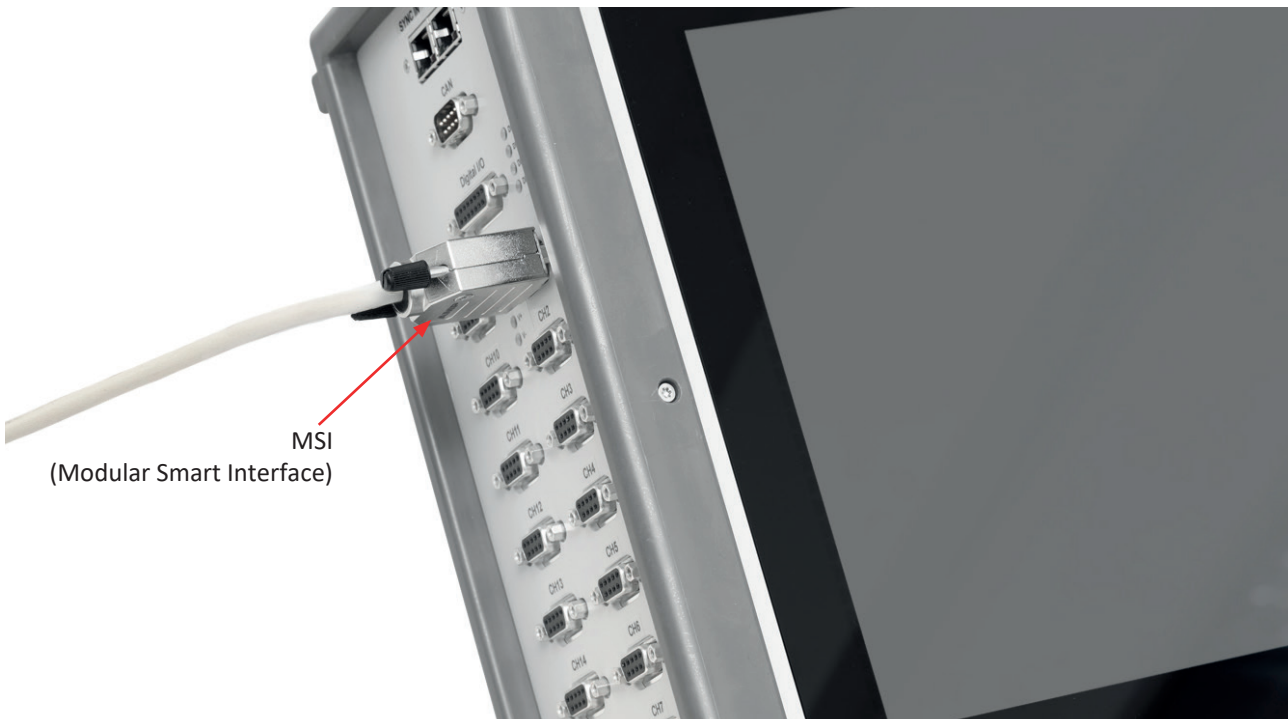
Signal connection via MSI (Modular Smart Interface)

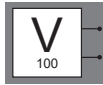
General MSI functionality

Each MSI is a signal conditioner designed for a dedicated sensor type. By reading the TEDS chip, the measuring system gets any information necessary to adjust the amplifier accordingly.

The user doesn't have to worry about it, he automatically gets the right measuring ranges with the right unit displayed.

For traceability, important data, such as serial number or calibration date, are also read out and if necessary additionally stored with the measurement data file.



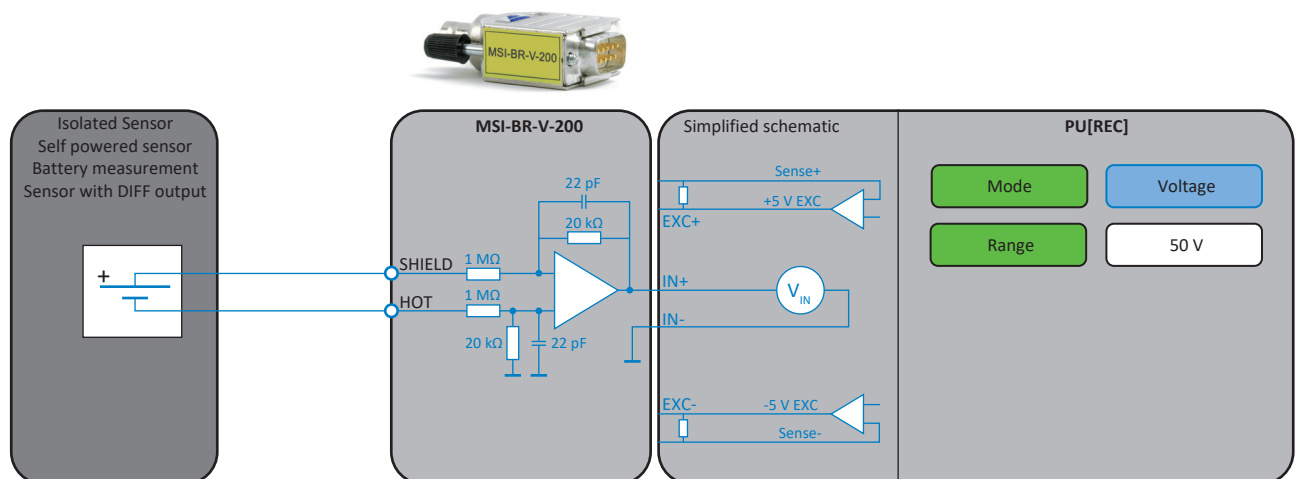


Voltage (<50 V) via

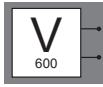


MSI-BR-V-200

| MSI-BR-V-200 | | | | |
|---|---|------|-------|---------------------|
| Sensor connection | BNC | | | |
| Input attenuation | 50 ±0.5 % | | | |
| Input type | Differential | | | |
| Rated input voltage to earth according to IEC/EN 61010-2-30 | 33 V _{RMS} , 70 V _{DC} , 46.7 V _{PK} | | | |
| Common mode voltage | IN+ and IN-: -200 V to +180V | | | |
| Overtoltage protection | ±250 V | | | |
| Input impedance IN+ | 1 MΩ | | | |
| Input impedance IN- | 1 MΩ | | | |
| Gain drift | typ. 25 ppm/K (max. 40 ppm/K) | | | |
| Input Offset drift | 200 μV/K | | | |
| Bandwidth (-3dB) | 60 kHz | | | |
| TEDS | For adapter identification and calibration data | | | |
| Voltage ranges | ±200 V; ±100 V; ±40 V; ±20 V | | | |
| DC accuracy: | ±0.05 % of reading ±20 mV | | | |
| Signal-to-noise ratio; spurious-free SNR; | SNR | SFDR | ENOB | Noise _{pp} |
| Effective number of Bits; Noise mV _{pp} | [dB] | [dB] | [Bit] | [mV _{pp}] |
| Sample rate | | | | |
| 5 kS/s | 105 | 130 | 17.7 | 6.2 |
| 10 kS/s | 102 | 125 | 17.3 | 8.2 |
| 20 kS/s | 99 | 125 | 16.7 | 12.5 |
| 50 kS/s | 95 | 120 | 16.1 | 21 |
| 100 kS/s | 92 | 120 | 15.6 | 29 |
| 200 kS/s | 89 | 115 | 15.1 | 47 |
| Typical CMRR | 100 dB @ 100 Hz 60 dB @ 10 kHz | | | |



MAIN SYSTEM

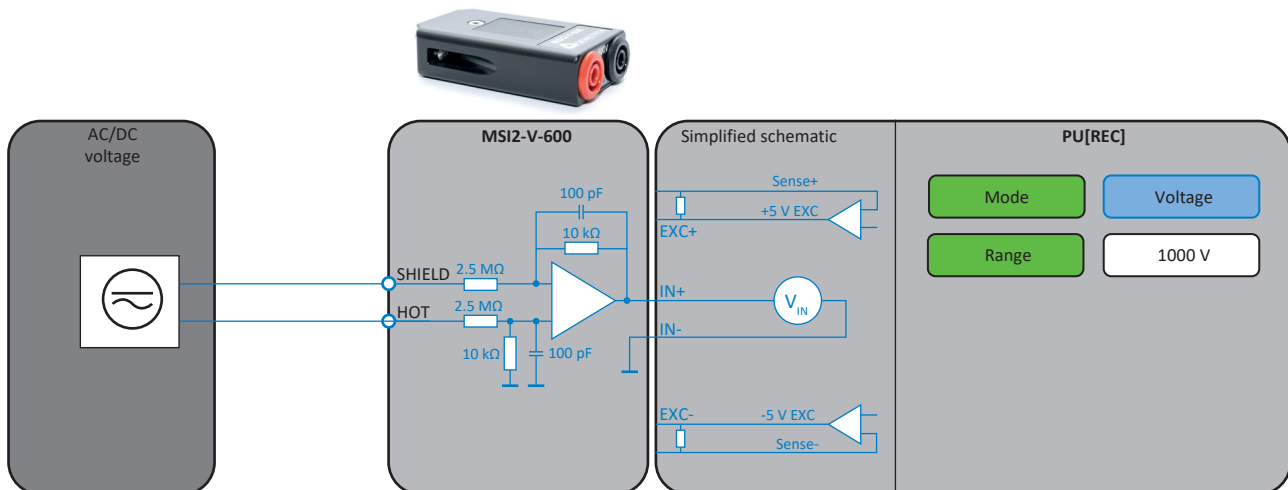


High voltage via



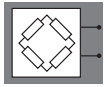
MSI2-V-600

| MSI2-V-600 | | | | | |
|---|--|---------------------------|------|-------|---------------------|
| Sensor connection | 4 mm safety banana sockets | | | | |
| Input attenuation | 250 ±0.5 % | | | | |
| Input type | Differential | | | | |
| Rated input voltage to earth according IEC/EN 61010-2-30 | 300 V CAT III / 600 V CAT II | | | | |
| Common mode voltage | ±1000 V | | | | |
| Overvoltage protection | 1500 V _{PK} / 1000 V _{RMS} (1 min) | | | | |
| Input impedance | 5 MΩ differential / 2.5 MΩ to earth | | | | |
| Gain drift | typ. 25 ppm/K (max. 40 ppm/K) | | | | |
| Input Offset drift | 200 μV/K | | | | |
| Bandwidth (-3dB) | 60 kHz | | | | |
| TEDS | For adapter identification and calibration data | | | | |
| Voltage ranges | ±1000 V; ±500 V; ±200 V; ±100 V | | | | |
| Accuracy | DC to 1 kHz | ±0.1 % of reading ±100 mV | | | |
| | >1 kHz to 5 kHz | ±0.5 % of reading ±100 mV | | | |
| | >5 kHz to 10 kHz | ±1 % of reading ±100 mV | | | |
| Signal-to-noise ratio; spurious-free SNR; Effective number of Bits; Noise mV _{PP} | | SNR | SFDR | ENOB | Noise _{PP} |
| | Sample rate | [dB] | [dB] | [Bit] | [mV _{PP}] |
| | 5 kS/s | 102 | 130 | 16.7 | 37.4 |
| | 10 kS/s | 99 | 127 | 16.2 | 51.2 |
| | 20 kS/s | 96 | 122 | 15.7 | 77 |
| | 50 kS/s | 92 | 119 | 15.0 | 126 |
| | 100 kS/s | 89 | 117 | 14.6 | 177 |
| | 200 kS/s | 87 | 113 | 14.1 | 265 |
| Typical CMRR | 74 dB @ 100 Hz | | | | |
| | 50 dB @ 10 kHz | | | | |



CAUTION:

Voltage measurement up to 600 V_{RMS} only with safety banana plug cords!



Strain gauge measurement via



MSI2-STG

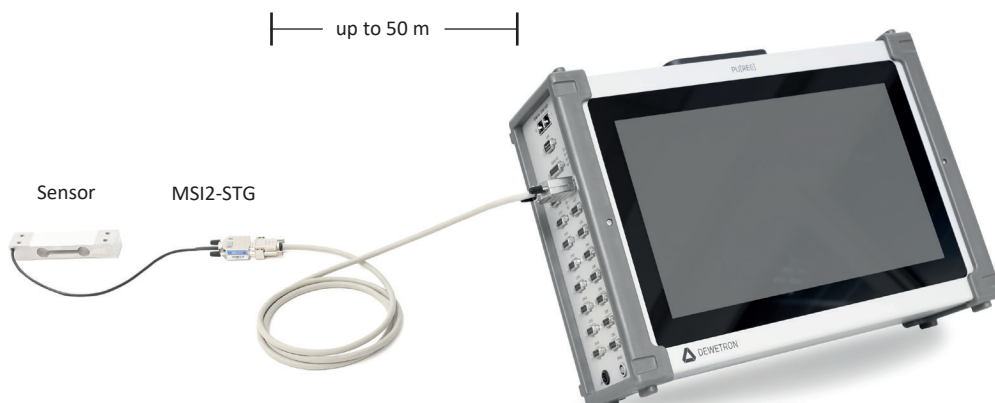
- > Full, half or quarter bridge
- > 120 and 350 Ω quarter bridge
- > 5 V or 10 V excitation with remote sense
- > Simple connection without soldering

| MSI2-STG | | | | |
|--|--|------|-------|-----------------------------|
| Input range | 20 mV/V <small>at 5V excitation</small> | | | |
| Sensor excitation voltage | 5 V or 10 V (± 5 V); remote sense support | | | |
| Maximum current | 40 mA per channel | | | |
| Protection | Continuous short to ground; short circuit limit is 70mA | | | |
| Supported bridge-types | Full bridge 4 or 6-Wire Half bridge 3 or 5-Wire Quarter bridge 3-Wire; 120 Ω and 350 Ω bridge completion | | | |
| DC accuracy | ± 0.2 % of reading ± 5 μ V/V | | | |
| Bandwidth (-3 dB) | 60 kHz | | | |
| Signal-to-noise ratio; spurious-free SNR; Effective number of Bits; Noise μ V/V _{pp} | 20 mV/V range | | | |
| | SNR | SFDR | ENOB | Noise _{pp} |
| Sample rate | [dB] | [dB] | [Bit] | [μ V/V _{pp}] |
| 5 kS/s | 101 | 124 | 16.5 | 0.88 |
| 10 kS/s | 98 | 125 | 16.0 | 1.4 |
| 20 kS/s | 95 | 123 | 15.5 | 1.9 |
| 50 kS/s | 91 | 120 | 14.9 | 3.3 |
| 100 kS/s | 88 | 115 | 14.4 | 4.5 |
| 200 kS/s | 86 | 110 | 13.9 | 7 |
| Drift | Offset: 0.4 μ V/°C; Gain: max 50 ppm/°C | | | |
| Sensor connection | Push-in spring connection; 0.14 to 0.5mm ² ; AWG 26 to 20 | | | |
| TEDS | For adapter identification and calibration data | | | |

The MSI2-STG is designed to connect nearly every strain gauge sensor.

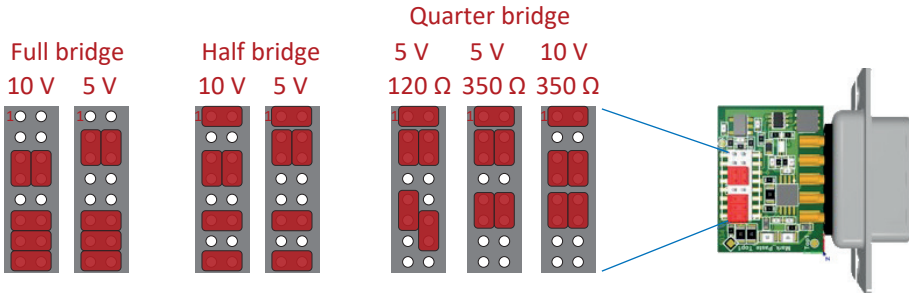
Various bridge-types can be configured by jumper. That makes it very flexible and an ideal solution for strain gauge measurement on **fixed installations**.

It is also a perfect solution for **harsh electronic environment**. Because this tiny amplifier can be mounted directly next to the sensor with very short cables in between. The signal is immediately amplified by a factor of 50. This reduces the impact of electromagnetic disturbances by the same factor. The maximum cable length between MSI and the PUREC is 50 meters.



MAIN SYSTEM

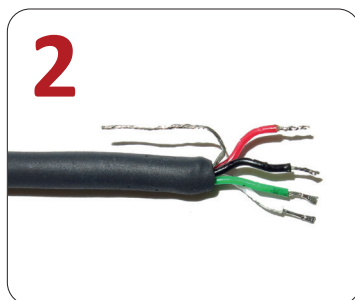
Jumper settings



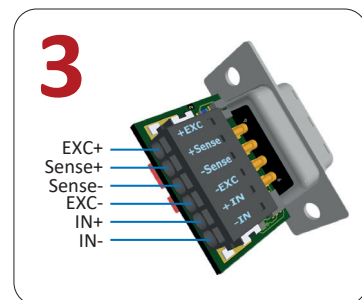
Connecting a sensor



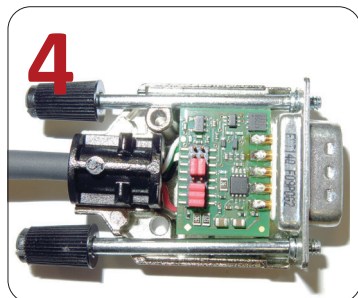
1 Check the sensor datasheet and determine the correct connection.



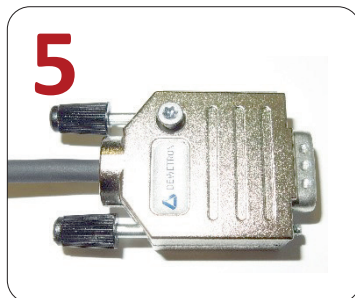
2 Prepare the sensor cable



3 Connect the cable to the PCB; the shield must be placed between housing and plastic.



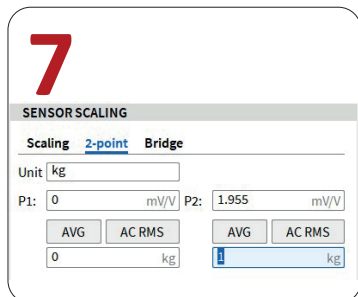
4 Apply the jumper according to the sensor



5 Close the housing

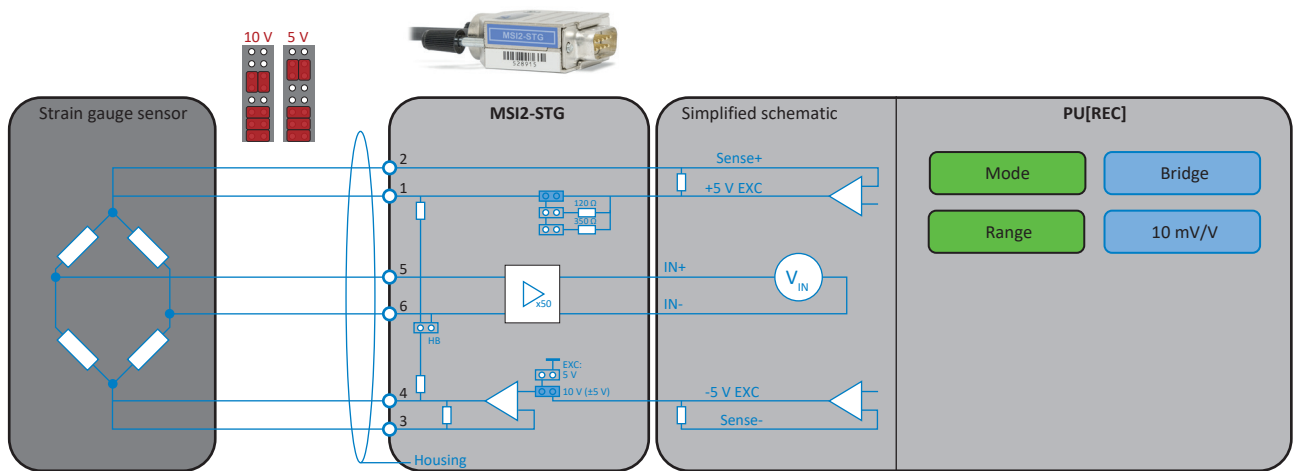


6 Connect the sensor directly or via extension cable

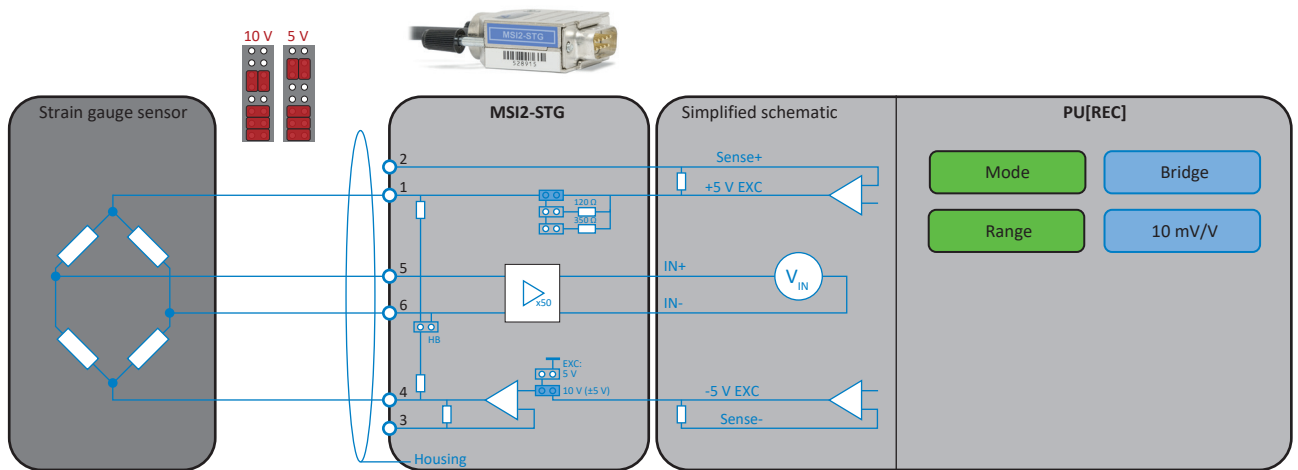


7 MS12-STG is detected automatically. Just apply sensor scaling.

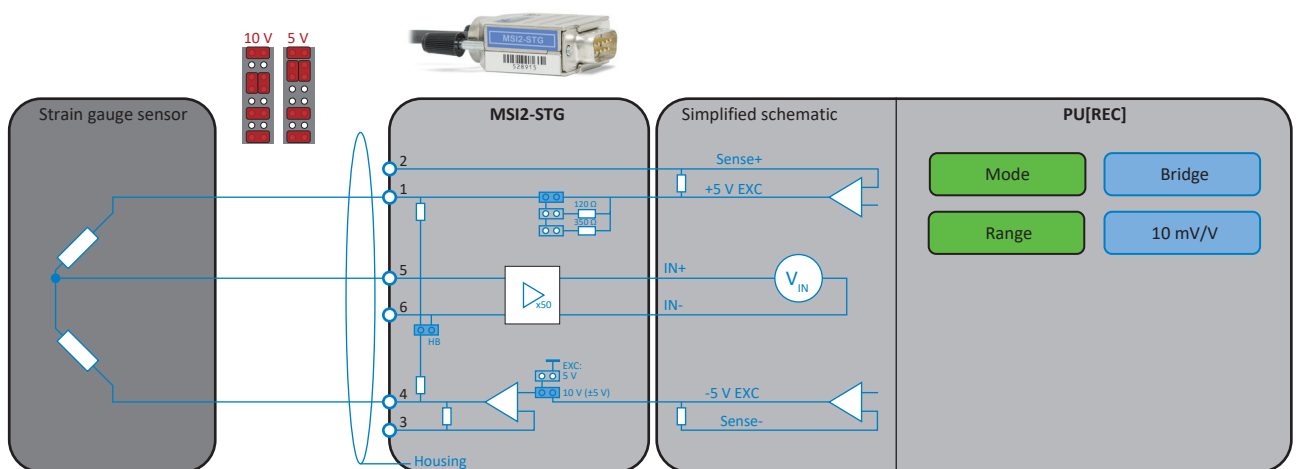
Full bridge 6-wire



Full bridge 4-wire

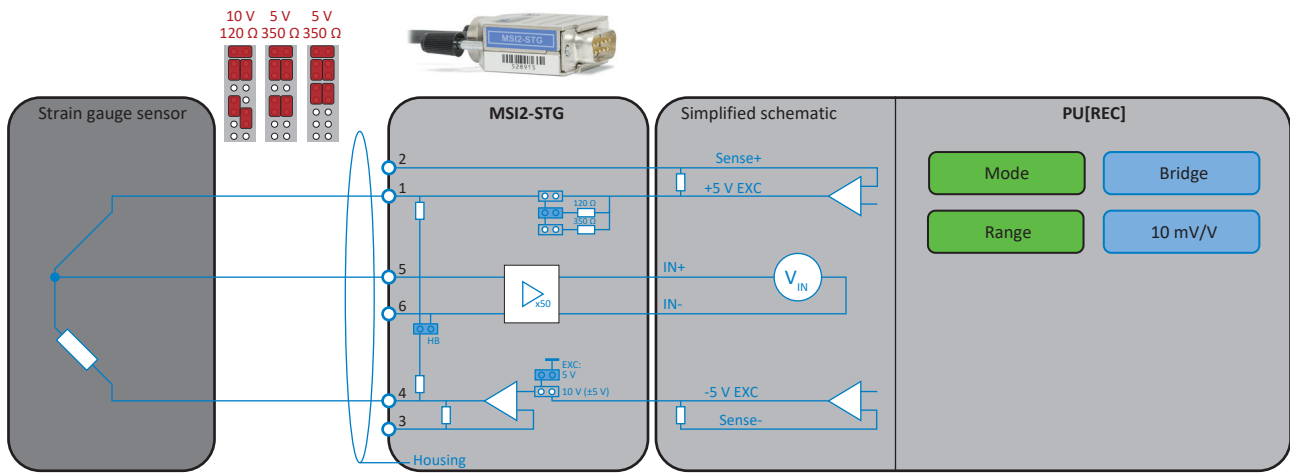


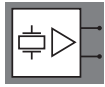
Half bridge 3-wire



MAIN SYSTEM

Quarter bridge 3-wire



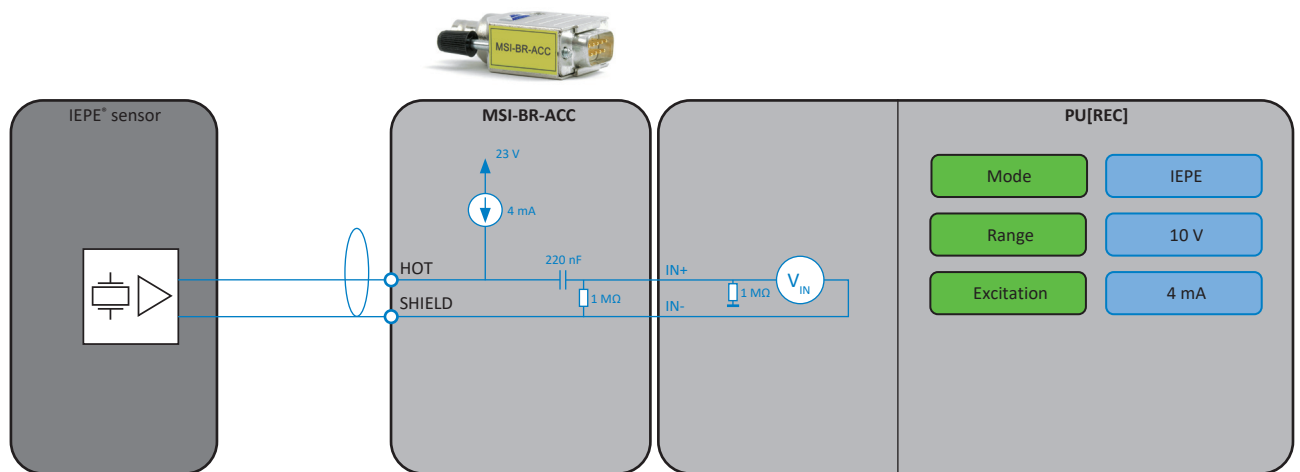


IEPE® via

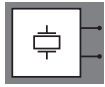


MSI-BR-ACC

| MSI-BR-ACC | | | | |
|--|---|------|-------|-------------------------------|
| Input Range | ± 10V | | | |
| Sensor Excitation | 4 mA ±10 % | | | |
| Compliance voltage | >23 V | | | |
| Accuracy | 30 Hz to 30 kHz: 0.2 % | | | |
| Power consumption | Max. 380 mW | | | |
| Input coupling | AC 1.4 Hz | | | |
| Bandwidth | 70 kHz <small>limited by instrument</small> | | | |
| Signal-to-noise ratio; spurious-free SNR; Effective number of Bits; Noise $\mu\text{V}/V_{\text{PP}}$ | SNR | SFDR | ENOB | Noise $_{\text{PP}}$ |
| Sample rate | [dB] | [dB] | [Bit] | $[\mu\text{V}/V_{\text{PP}}]$ |
| 5 kS/s | 101 | 124 | 17.1 | 0.88 |
| 10 kS/s | 98 | 125 | 16.6 | 1.4 |
| 20 kS/s | 83 | 123 | 14.1 | 1.9 |
| 50 kS/s | 79 | 120 | 13.5 | 3.3 |
| 100 kS/s | 76 | 115 | 13.0 | 4.5 |
| 200 kS/s | 73 | 110 | 12.5 | 7 |
| Sensor connection | BNC | | | |
| TEDS | For adapter identification | | | |



MAIN SYSTEM

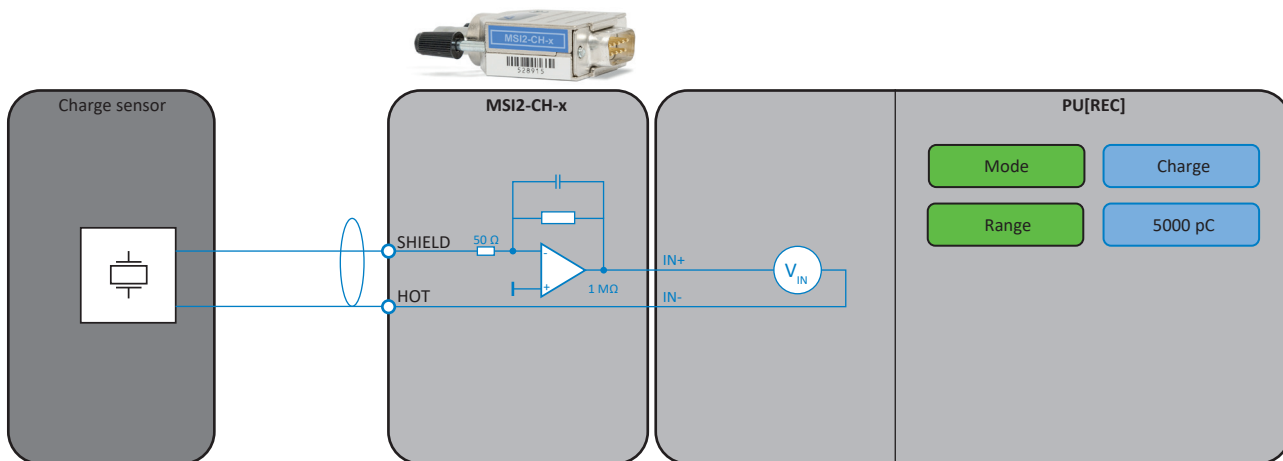


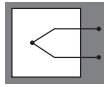
Charge via



MSI2-CH-x

| MSI2-CH-x | | | | |
|--|---|------------|------|-------|
| Input Range | MSI2-CH-5 | ±5 000pC | | |
| | MSI2-CH-100 | ±100 000pC | | |
| Accuracy | 3 Hz to 30 kHz: 0.5 % | | | |
| Gain drift | 50 ppm/ °C | | | |
| Input coupling | AC 0.14 Hz | | | |
| Bandwidth | 70 kHz <small>limited by instrument</small> | | | |
| Signal-to-noise ratio; spurious-free SNR; Effective number of Bits; Noise pC_{pp} | | SNR | SFDR | ENOB |
| | Sample rate | [dB] | [dB] | [Bit] |
| | 10 kS/s | 101 | 130 | 17.1 |
| | 20 kS/s | 99 | 130 | 16.7 |
| | 50 kS/s | 95 | 125 | 16.0 |
| | 100 kS/s | 92 | 120 | 15.5 |
| | 200 kS/s | 89 | 115 | 15.1 |
| Sensor connection | BNC | | | |
| TEDS | For adapter identification and calibration data | | | |





Thermocouple via



MSI2-TH-x

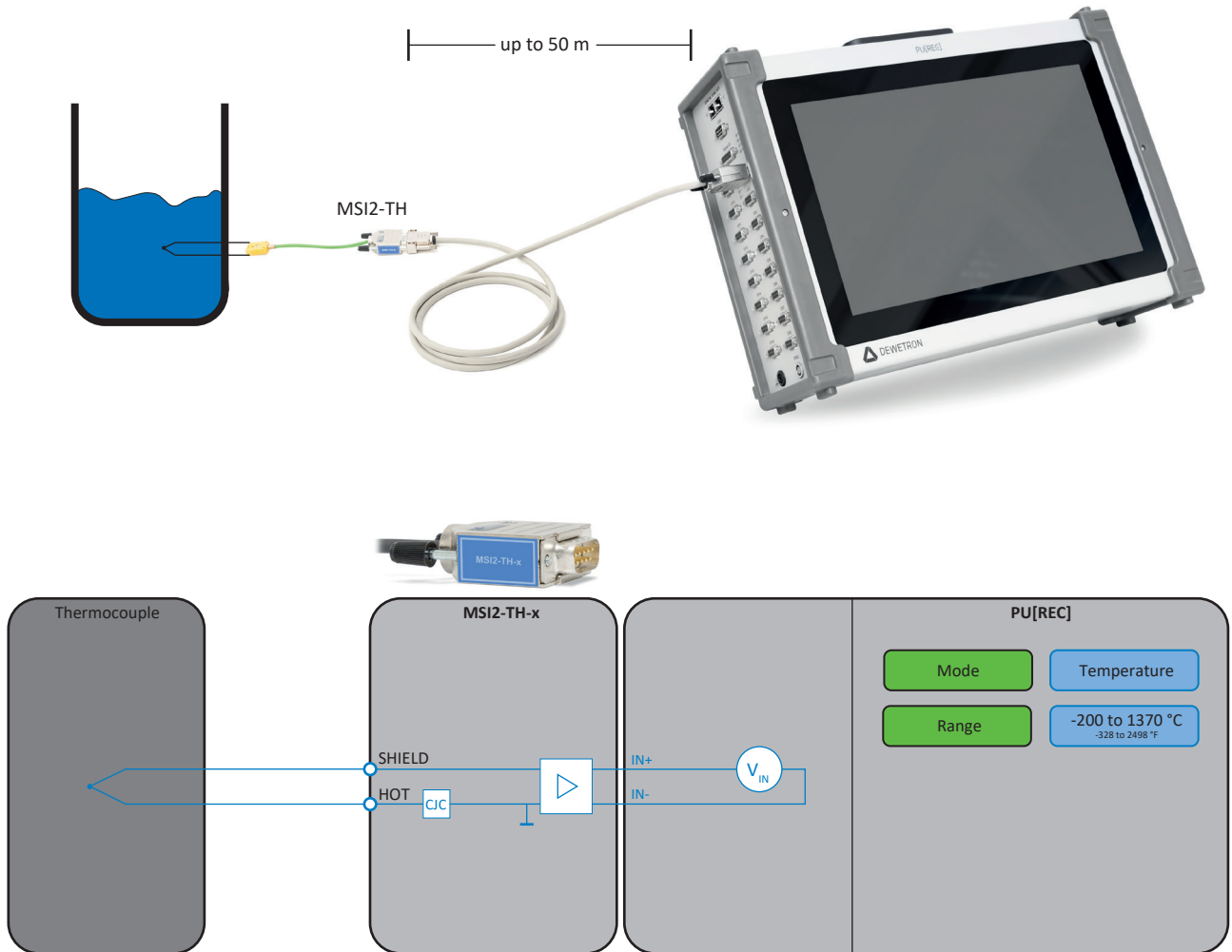
| MSI2-TH-x | |
|--|--|
| Thermocouple types | Type K, J, T, C |
| Sensor connection | 1m cable with standard miniature thermocouple connector according to TC type |
| Pre-amplifier | Integrated; cable drive capability 50 m |
| Open thermocouple detection | 100 MΩ pullup; broken sensor shows positive full scale |
| CJC accuracy | 1.0 °C |
| Input impedance | >10 Ω |
| Bias current | 50 nA |
| Linearization | Through software according to sensor type |
| Bandwidth | 30 kHz |
| Typical peak to peak noise for sensor type K | |
| 1 kHz bandwidth | 0.50 °C |
| 100 Hz bandwidth | 0.25 °C |
| 10 Hz bandwidth | 0.04 °C |
| TEDS | For adapter identification and calibration data |

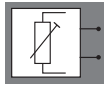
| Accuracy incl. CJC error | | |
|--------------------------|-----------------|----------------------------------|
| MSI2-TH-K | Type K | (DIN-EN 60584-1) |
| Input ranges | | -200 to 1370 °C [-328 to 2498°F] |
| Accuracy incl. CJC error | -200 to -100 °C | ±1.2 °C |
| | -100 to 1370 °C | ±0.6 °C |
| MSI2-TH-J | Type J | (DIN-EN 60584-1) |
| Input ranges | | -210 to 1200 °C [-346 to 2192°F] |
| Accuracy incl. CJC error | -200 to -100 °C | ±1.1 °C |
| | -100 to 1200 °C | ±0.6 °C |
| MSI2-TH-T | Type T | (DIN-EN 60584-1) |
| Input ranges | | -270 to 400 °C [-454 to 752°F] |
| Accuracy incl. CJC error | -250 to -100 °C | ±3 °C |
| | -100 to 400 °C | ±0.8 °C |
| MSI2-TH-C | Type C | (ASTM E988-96) |
| Input ranges | | 0 to 2300 °C [32 to 4172°F] |
| Accuracy incl. CJC error | 0 to 1600 °C | ±1 °C |
| | 1600 to 2300 °C | ±1.5 °C |

MAIN SYSTEM

Functional description

The MSI2-TH-x series is the improved version of the previous MSI series. The accuracy is approximately 3 times higher than at the previous version. A calibrated high precision cold junction compensation is included in the adapter. It comes with an integrated preamplifier that boosts the tiny thermocouple voltage up to a few volts. That's why the V2 series can be directly placed next to the sensor. Use extension cables up to 50 m between the MSI and the PUREC system instead of having long thermocouple lines with small signal level. That can greatly improve your signal quality in harsh electronic environment.





RTD via



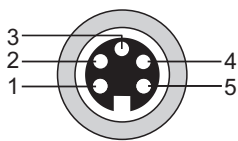
MSI-BR-RTD

- > Support of Pt100, Pt200, Pt500, Pt1000, Pt2000
- > 2-, 3- or 4 wire connection

| MSI-BR-RTD | |
|--------------------------------------|---|
| Supported sensors | Resistance, Pt100, Pt200, Pt500, Pt1000, Pt2000 |
| Temperature range | -200 °C to 850 °C |
| Constant current | 1.25 mA |
| Constant current accuracy | ±0.02 % from calibrated value |
| Constant current drift | 22 ppm/ °C |
| Linearization | Through software according to sensor type |
| Connection types | 2-, 3- or 4-wire |
| Typical peak to peak noise for Pt100 | |
| 1 kHz bandwidth | 0.25 °C |
| 100 Hz bandwidth | 0.08 °C |
| 10 Hz bandwidth | 0.02 °C |
| Power consumption | |
| Sensor connection | 5-pin BINDER connector series 712 |
| TEDS | For adapter identification and calibration data |

| Accuracy | | | |
|----------|-----------------------|----------------|----------------------------|
| Type | | Range | Accuracy |
| | Pt100 (DIN EN 60751) | -200 to 850 °C | 0.05 % of reading ±0.65 °C |
| | Pt200 (DIN EN 60751) | -200 to 850 °C | 0.05 % of reading ±0.36 °C |
| | Pt500 (DIN EN 60751) | -200 to 850 °C | 0.04 % of reading ±0.17 °C |
| | Pt1000 (DIN EN 60751) | -200 to 850 °C | 0.04 % of reading ±0.11 °C |
| | Pt2000 (DIN EN 60751) | -200 to 260 °C | 0.04 % of reading ±0.10 °C |

Sensor connector

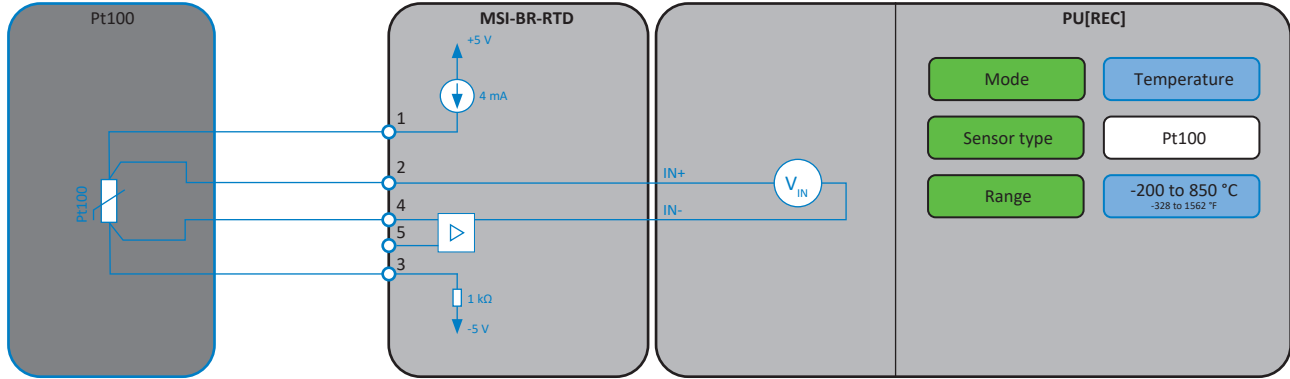


Pin assignment:

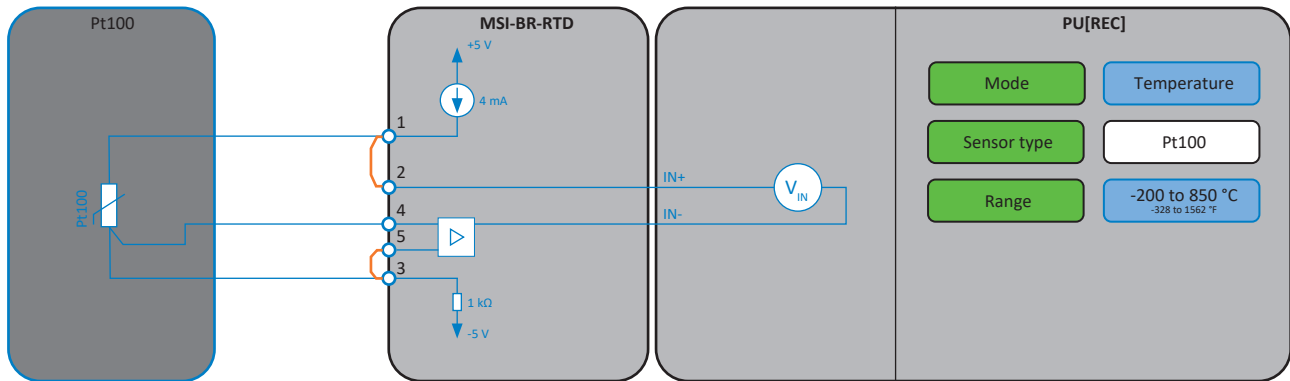
- 1 EXC+
- 2 SENSE+
- 3 EXC-
- 4 SENSE-
- 5 3-wire connector

MAIN SYSTEM

RTD 4-wire sensor

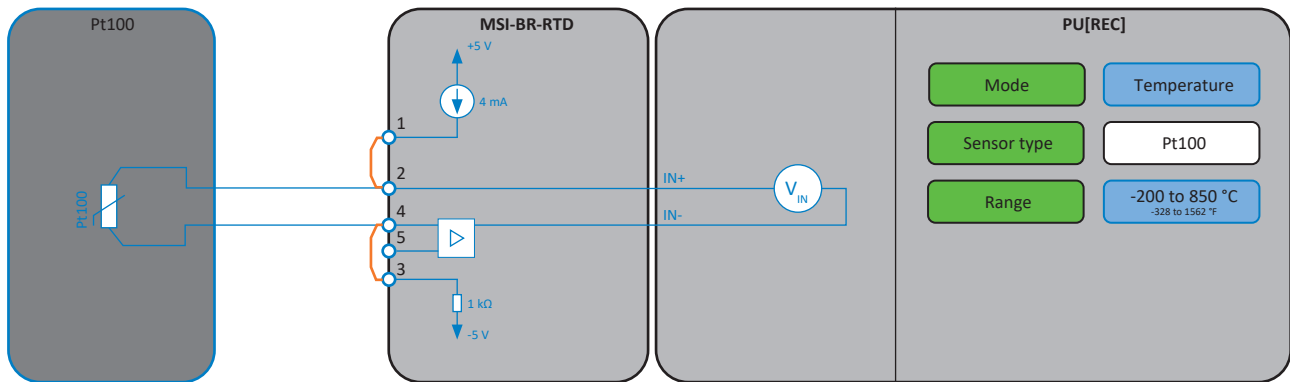


RTD 3-wire sensor

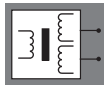


external solder bridge

RTD 2-wire sensor



external solder bridge



LVDT via



MSI2-LVDT

| MSI2-LVDT | |
|-----------------------|--|
| Transducer type | LVDT with 5 or 6 electrical connections (wires) |
| Sensor connection | Soldering |
| Excitation voltage | 3 V _{RMS} |
| Excitation frequency | 2.5 kHz, 5 kHz, 18 kHz selectable by jumper (H, M, L; ±5 %) |
| Output at stroke ends | 280 mV/V to 1666 mV/V at full scale (+/-5 V), adjustable by gain-potentiometer |

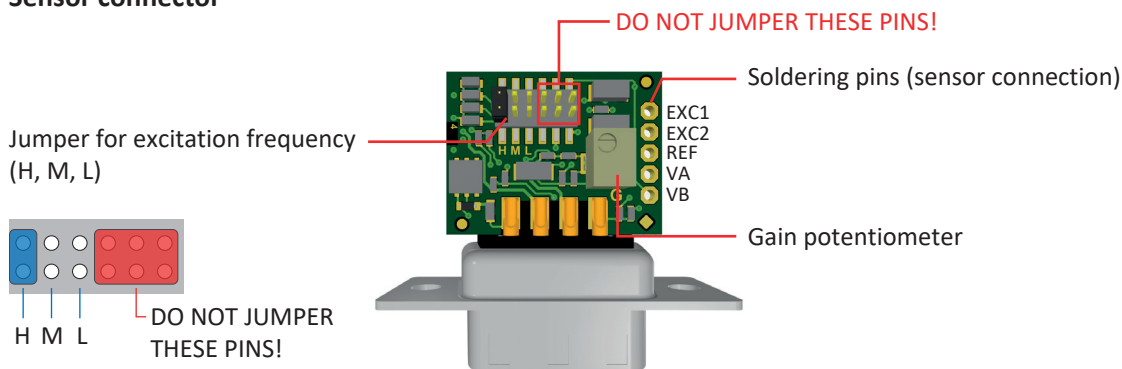
Functional description

The MSI2-LVDT is a high reliability conditioner for measurement of displacement with an LVDT (Linear Variable Differential Transformer). It can be used with 5- or 6-wire transducers.

The MSI2-LVDT provides the sine wave sensor excitation and converts the sensor output into a linear voltage output. With the gain potentiometer the MSI2-LVDT can be adjusted to a measuring range from 280 mV/V to 1666 mV/V. This allows a rough adjustment to the sensor. The best way is to bring the sensor to the end position and adjust the output to about 4.5 V. The exact adjustment of the sensor should be done by two point scaling in the software.

Thereby the MSI2-LVDT sensitivity is equivalent to 5 V/stroke end length (in mm or inch) [V/mm(inch)]. Once that is done apply the strain relief brackets and close the MSI.

Sensor connector

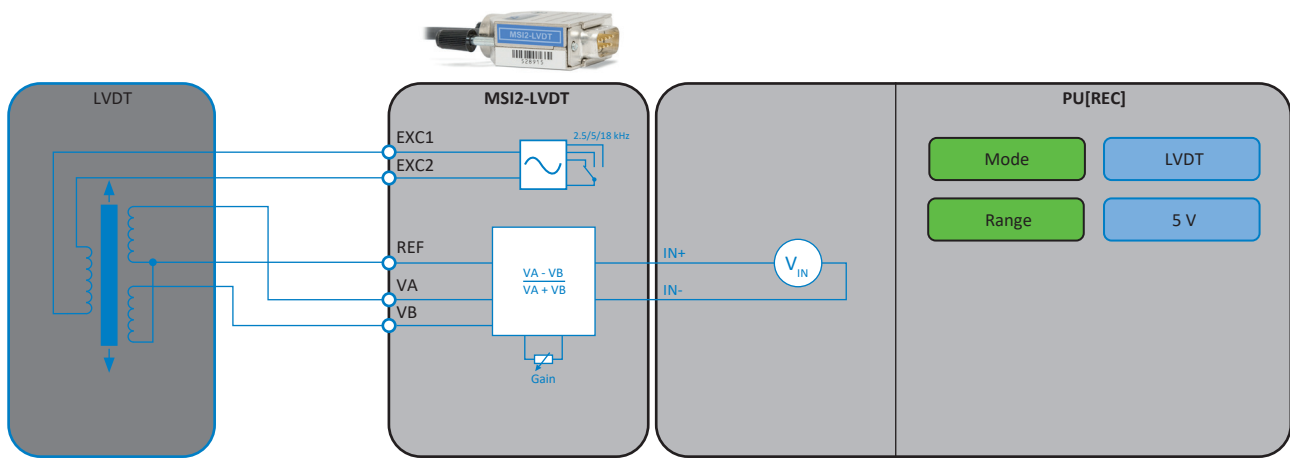


H = 18 kHz

M = 5 kHz

L = 2.5 kHz

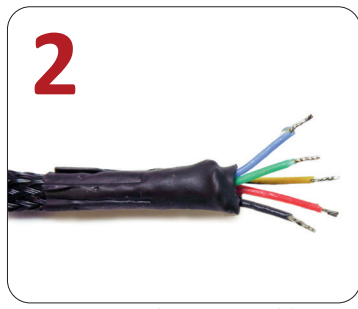
MAIN SYSTEM



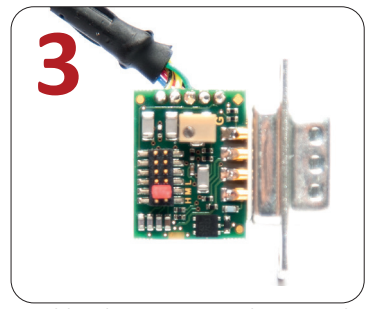
Connecting a sensor



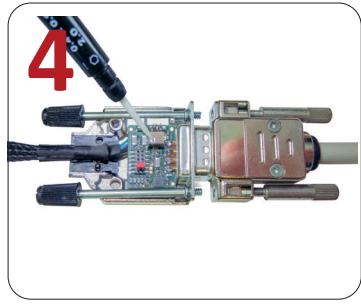
1 Check the sensor datasheet and determine the correct connection.



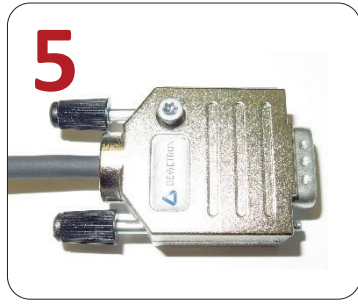
2 Prepare the sensor cable



3 Solder the wires onto the printed circuit board.



4 Connect the MSI2-LVDT to the measurement system with an extension cable. Adjust gain-potentiometer roughly.



5 Close the housing.



6 Connect the sensor directly or via extension cable.

7

SENSOR SCALING

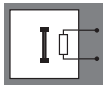
Scaling 2-point

Unit

P1: V V

| | | | |
|-----------------------------------|-----------------------------------|-----------------------------------|-----------------------------------|
| AVG | AC RMS | AVG | AC RMS |
| <input type="text" value="0"/> mm | <input type="text" value="5"/> mm | <input type="text" value="0"/> mm | <input type="text" value="5"/> mm |

Fine adjust sensor with sensor scaling.



4 to 20 mA sensor via

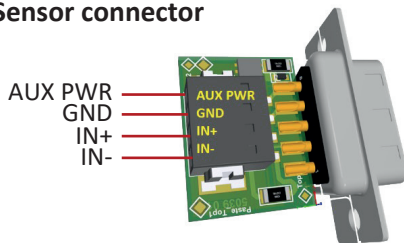
MSI2-LA-250R-20mA

- > Direct connection of loop powered sensors
- > Simple connection without soldering

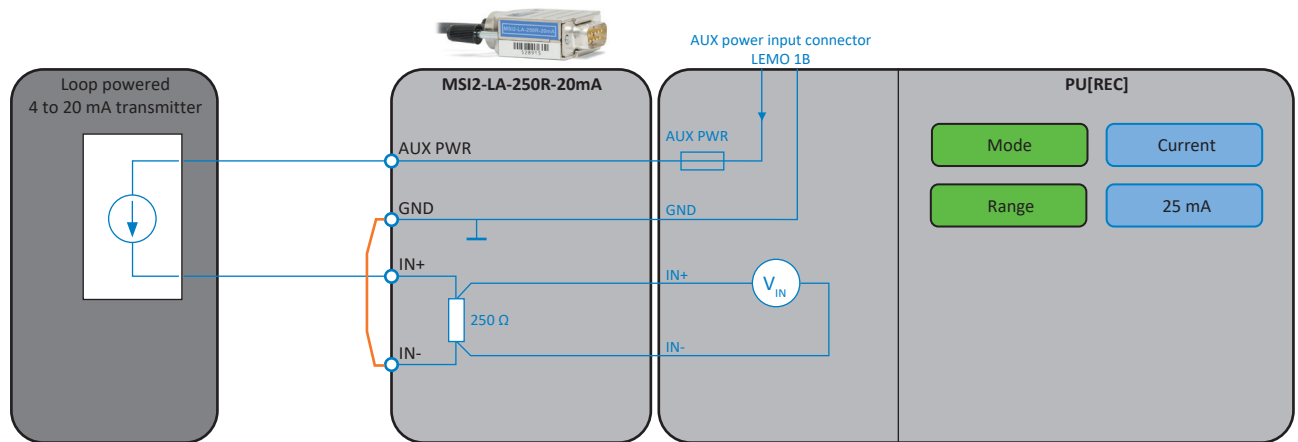


| MSI2-LA-250R-20mA | |
|---------------------|---|
| Supported sensors: | 4 to 20 mA; loop powered sensors |
| Sensor connection: | Push-in spring connection; 0.14 to 0.5 mm ² ; AWG 26 to 20 |
| Input Range: | ±25 mA |
| accuracy: | 0.05 % of reading ±4 μA |
| Excitation Voltage: | AUX Power; refer to simplified power schematic |
| Shunt resistor | 250 Ω; 0.4W; 25 ppm/°C |

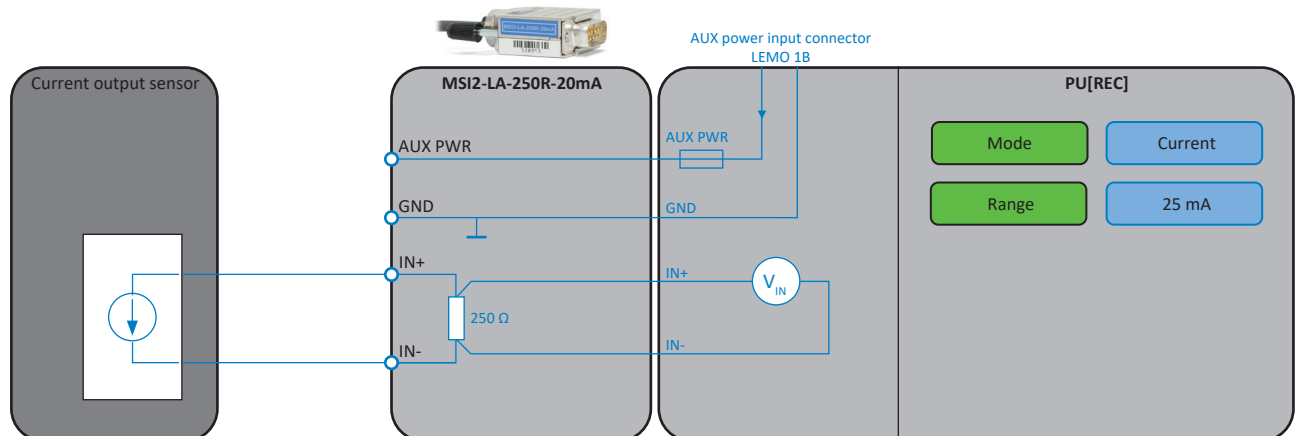
Sensor connector



Loop powered 4 to 20 mA transmitter



Current output sensor



MAIN SYSTEM

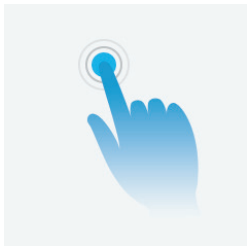
Operating with the Touchscreen

Touchscreen gestures

The PU[REC] is equipped with a bright 15.6" full HD wide screen multi-touch panel to control the instrument. You can use your fingers on the touchscreen, like you would on a smartphone. For example, drag the sidebar from the right side across the screen to open the channel setup.

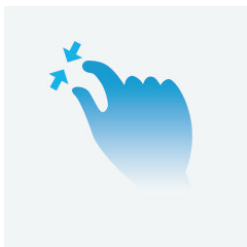
Tap? Swipe? Here's a glossary of touch gestures that you can use with the PU[REC].

Tap



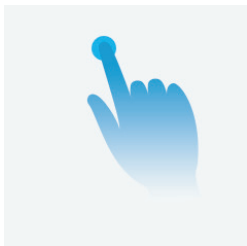
How to do it: Tap once on something.
What it does: Open, selects, or activates whatever you tap. Similar to clicking with a mouse.

Pinch or stretch



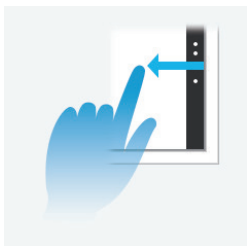
How to do it: Touch the screen with two fingers, and then move the fingers toward each other (pinch) or away from each other (stretch).
What it does: Zooms in or out of a graph or data.

Tap and hold



How to do it: Press your finger down and hold for about a second.
What it does: Rearranges objects on your main screen.

Swipe / Drag



How to do it: Drag your finger on the screen.
What it does:
- Scrolls through recorded data (like scrolling with a mouse).
- Drags the sidebar from the right side across the screen to open the channel setup

Further information on how to operate with OXYGEN please find in the corresponding user manual available at: <https://ccc.dewetron.com/pl/oxygen>

OXYGEN quickstart guide

Perform a measurement and export the data in just a few easy steps!

For a more detailed explanation of the OXYGEN software please refer to the OXYGEN Technical Reference Manual, which is available at <https://ccc.dewetron.com/pl/oxygen> or make sure to check out our latest PU[REC] videos on youtube available at <https://www.youtube.com/playlist?list=PLySNf48JXZNjxKw8XI6YwIFmOoC-hJ4dz> or scanning the QR code below.



Starting OXYGEN

When starting OXYGEN, the measurement screen is displayed. OXYGEN will instantly start to acquire data but will not store it yet. Figure 1 shows an overview of the measurement screen and some important buttons and menu tabs.

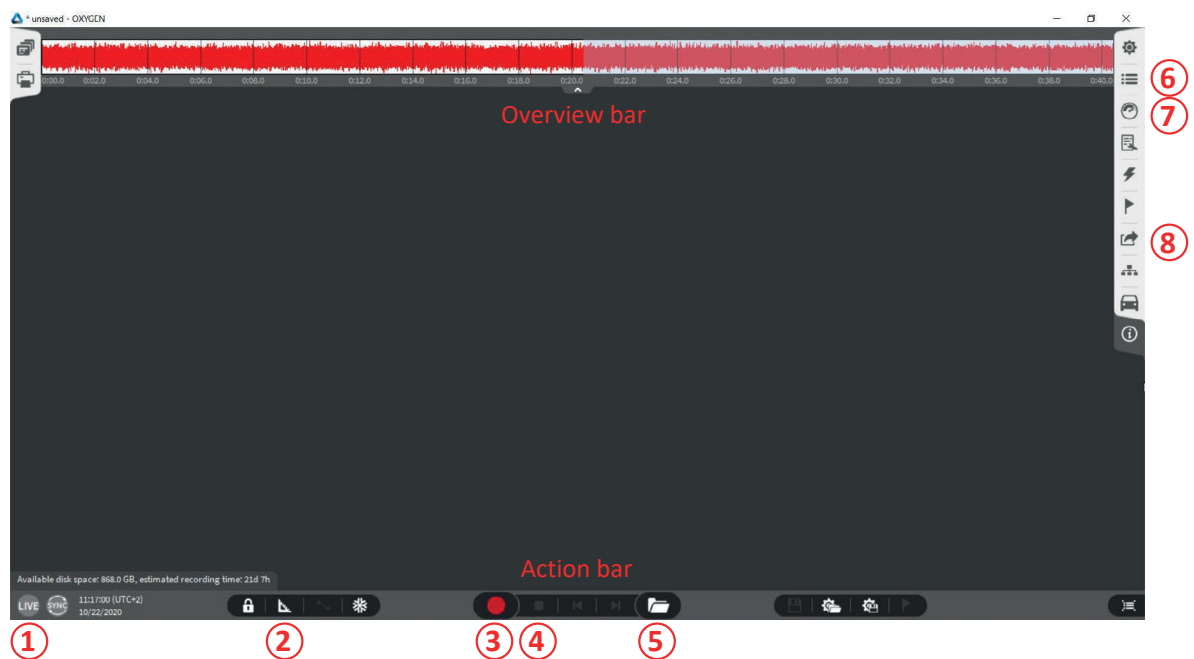


Figure 1

- 1 Software Mode Indicator
- 2 Design Mode
- 3 Record
- 4 Stop
- 5 Open Data File
- 6 Data Channel List Menu
- 7 Instruments Menu
- 8 Export Menu

Changing channel settings

The next step is to change the channel settings. By simply clicking on the channel name in the list, a new name can be entered. Also, by clicking on the gear button the channel setting will open, seen in Figure 4. There different settings are available, like a sensor scaling if needed. Just enter the unit and a scaling or sensitivity factor. Table scaling for a non-linear scaling is also available here. All settings are automatically saved when entered and do not have to be saved separately.

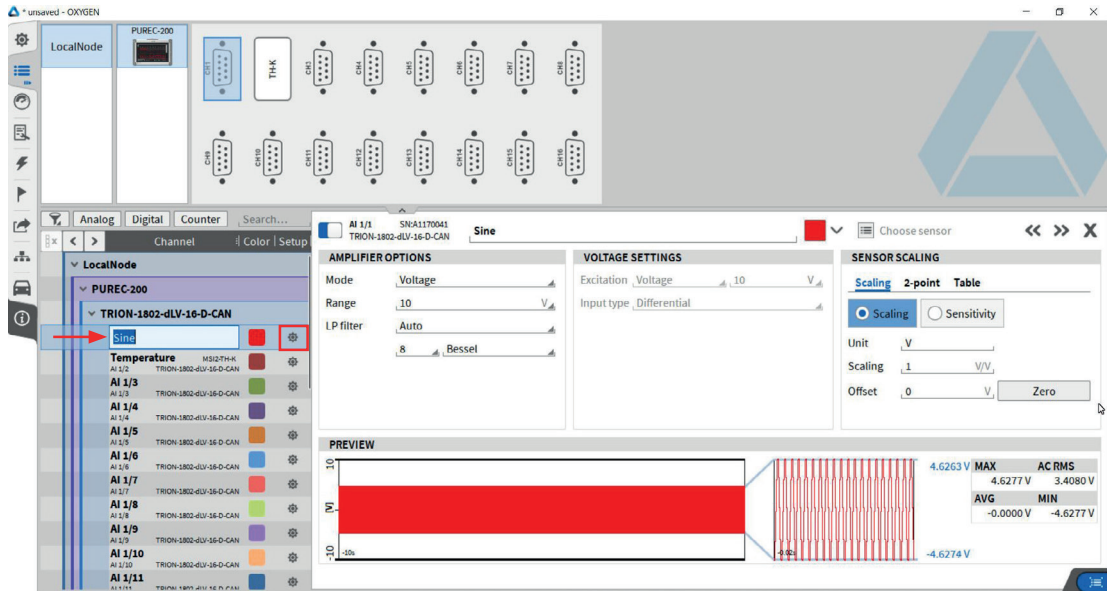


Figure 4

Design the measurement screen

After the channel settings are done, return to the measurement screen by again double clicking/tapping on the menu tab or swiping the menu to the right. Click or tap on the Instrument menu tab and drag and drop a recorder on the measurement screen. More instruments can be added and adjusted like this, when being in Design Mode (see 2 in Figure 1). Click on the Data Channel menu tab and add the signal by selecting the instrument and the signal to be shown or by drag and dropping the signal into the instrument. Disable the Design Mode.

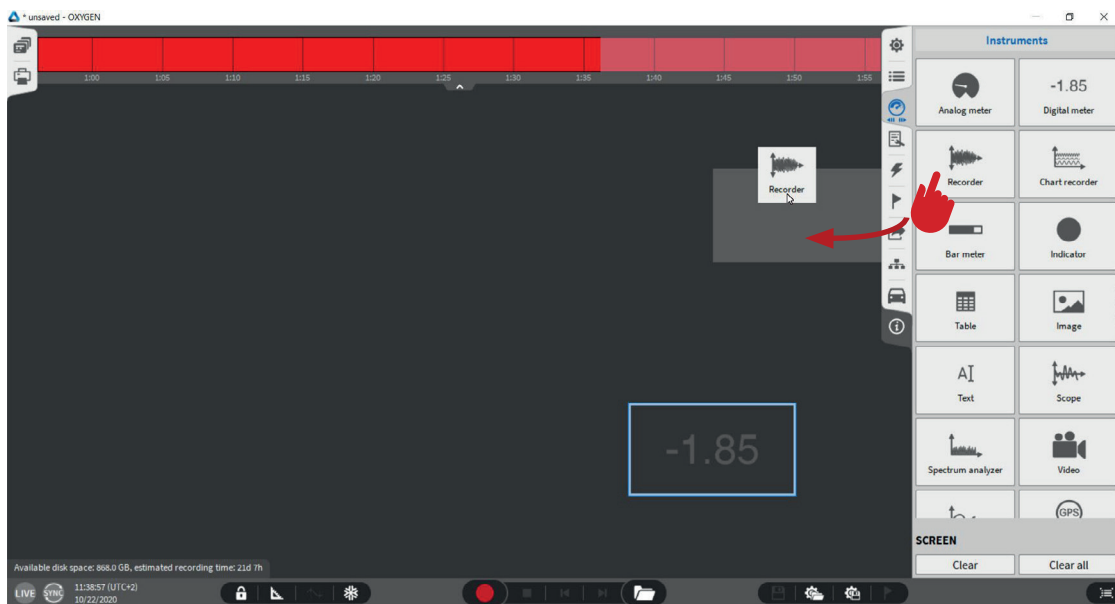


Figure 5

MAIN SYSTEM



Figure 6

Record

To start the recording simply click on the record button. The red border and the REC indicator seen in Figure 7 in the lower left corner displays, that the recording is going on. Click on the Stop button to stop the recording.

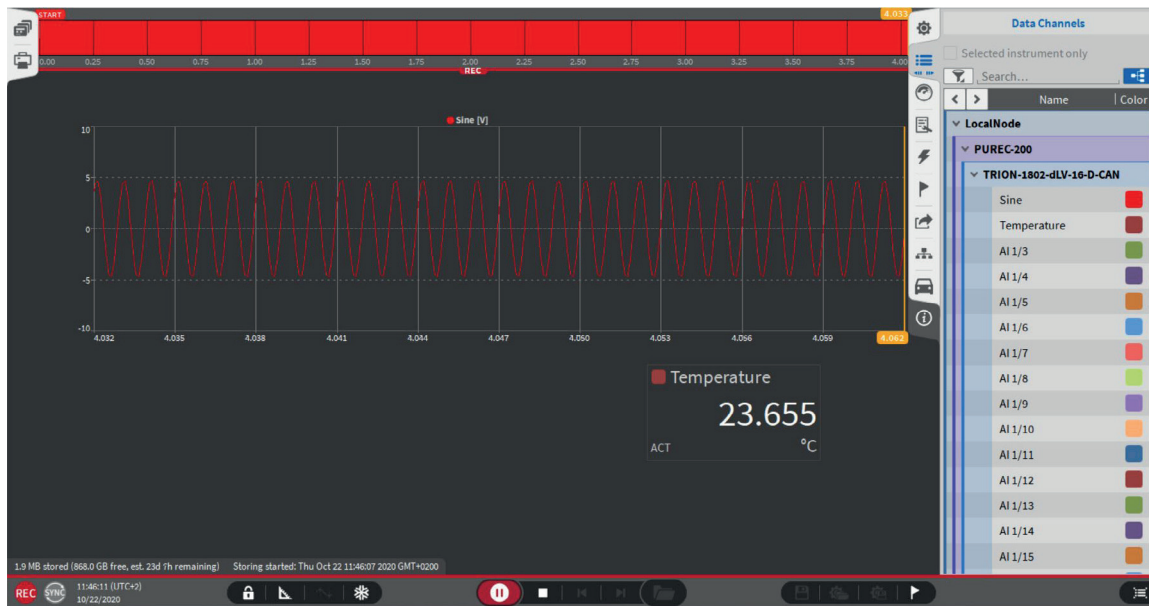


Figure 7

Open Datafile and Export

To open a datafile, click on the file button, and select the corresponding file (see Figure 8). The green border and PLAY indicator in the lower left corner indicate that a file is loaded for post-processing (see Figure 9). To export the data, click or tap on the Export Settings menu tab, select the desired format, channels to be exported and click on the export button seen in Figure 9.

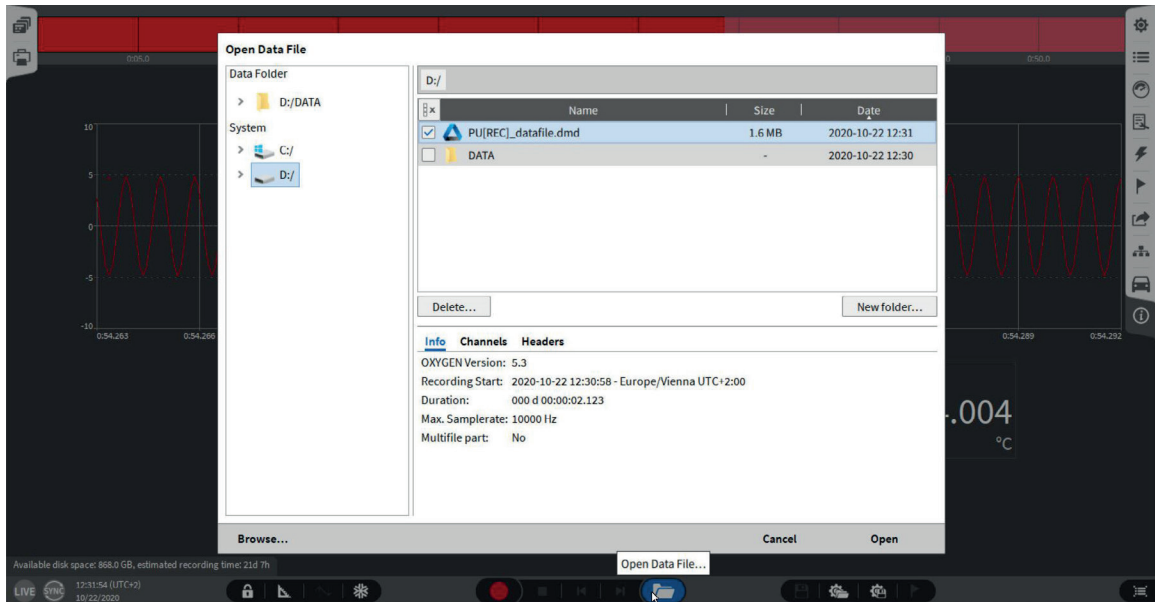


Figure 8



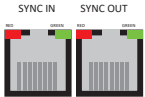
Figure 9

MAIN SYSTEM

Synchronization options

Synchronization via SYNC-BUS

The SYNC-BUS (SYNC IN, SYNC OUT) is used to synchronize two or more PU[REC] systems with up to 100 m distance between each node. The SYNC-BUS consists of two RJ-45 sockets. One socket being a synchronization OUT, whilst the other is used as synchronization IN.



LED indication

| | SYNC OUT | SYNC IN |
|-----------------------|---------------------|---------------------|
| RED (stable) | Clock detected | Receiving clock |
| GREEN (stable) | Acquisition running | Acquisition running |

Depending on the usage of the SYNC (input or output) the LED indicates if the system clock is available or received correctly from another system. The green LED indicates that the acquisition is running. If the acquisition stops the LED will be off.



Data transfer (independent from synchronization)

The network topology is the responsibility of the customer. Any topology supported by the operating system can be used. In theory, the normal company network can also be used. However, DEWETRON recommends the use of a separate network which is only used for data transmission.

NOTE:  Networked data acquisition (claiming multiple, distributed DEWETRON measurement systems) requires software option OXYGEN-NET (OXY-OPT-NET).

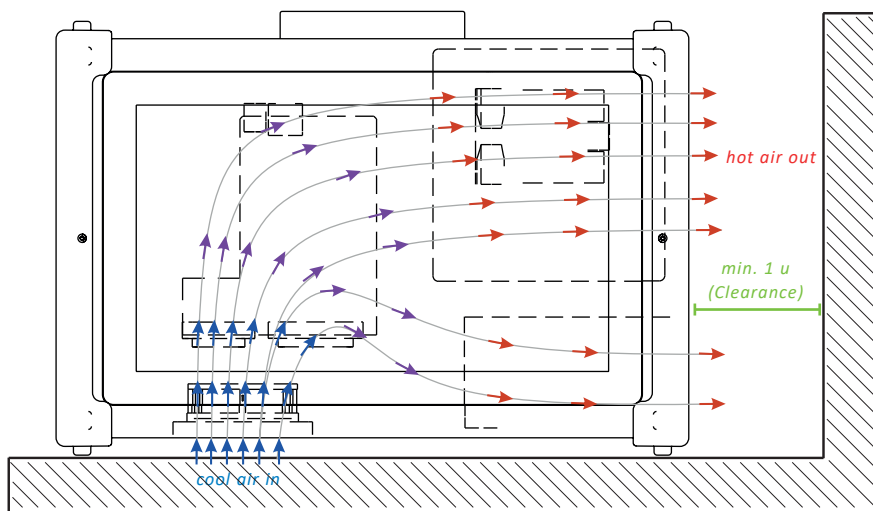
Cooling considerations

The intake vent of the PU[REC] is located at the bottom of the chassis, whereas the exhaust vent for the PU[REC] is at the right sidepanel of the chassis.

CAUTION: Adequate clearance between the chassis and surrounding equipment or blockages must be maintained to ensure proper cooling of the internals of the chassis!

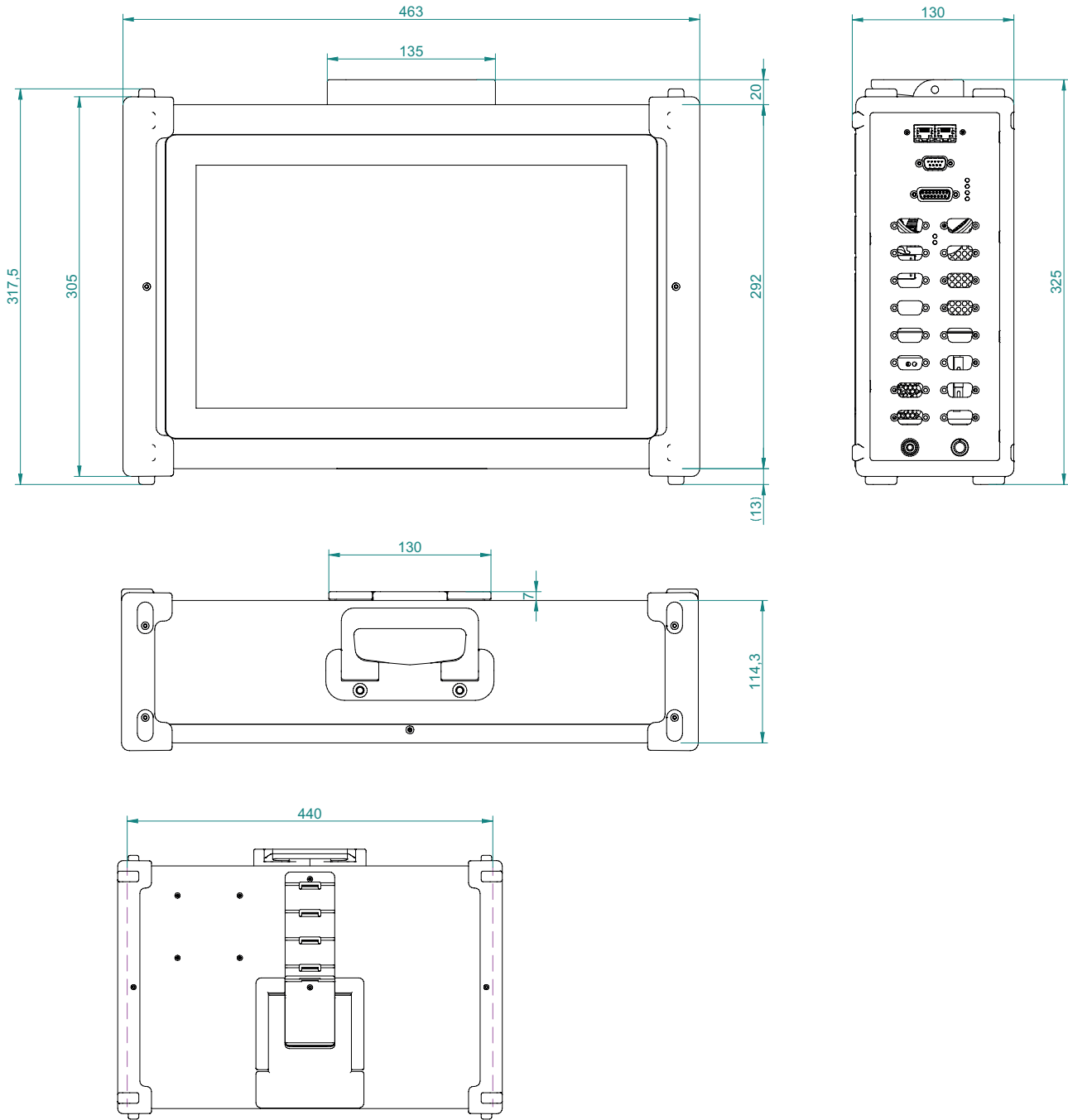


PU[REC] front view



MAIN SYSTEM

Dimensions



* Dimensions in mm
(1 inch = 25.4 mm)

Maintenance

Maintenance intervals

DEWETRON recommends following maintenance intervals:

| Actions | On demand | At least once a year | Every 5 years |
|---------------------|---------------------------------------|----------------------|---------------|
| Clean Filters | depending on environmental conditions | x | |
| Calibrate system | | x | |
| Change CPU FAN | | | x |
| Change Chassis FAN | | | x |
| Change CMOS battery | | | x |
| Change power supply | | | x |
| Change SSD | depending on SSD health status | | x |

Intervals may vary. Depending on environmental conditions, runtime, etc.

DEWETRON offers various service and upgrade plans including cleaning/exchanging fans/power supply/CPU cooler (if required), BIOS, firmware and driver updates as well as reliability upgrades and full functionality check. Please do not hesitate to ask DEWETRON or your local distributor for further information and pricing.

Removing the intake vent and cleaning the filter pad

Requirements:

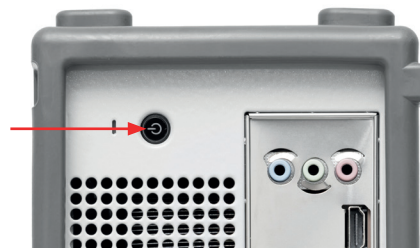
- > TORX T10 screw driver

WARNING: *DO NOT attempt to remove the intake vent when in operation!
POWER OFF the instrument first!*



1

Power off the instrument.



2

To access the filter pad simply loosen the screws on both sides of the intake vent with a TORX T10 screwdriver.

To clean the filter pad use a dry velocity stream of air. Afterwards, make sure to reinstall the filter pad and tighten the screws.



WARNING: *The maximum length for screws is 6 mm! If a screw gets lost, replace it with M3x6 countersunk head screws only. Otherwise internals may get damaged!*



MAIN SYSTEM

Letter of volatility

This describes the location and contents of volatile and non-volatile memory devices within the PU[REC].

Volatile memory

| Type | Size | User modifiable | Function | Process to delete |
|----------------------------|------------------------------------|-----------------|--------------------------------|-------------------|
| Innodisk M45I, DDR4 SODIMM | 8 GB module (16 x 512 MB chips) | Yes | RAM | Power OFF |
| Intel i3 8100, cache | 6 MB | No | Cache | Power OFF |
| DAQ board DDR3 | 512 MB | Yes | buffer for measurement data | Power OFF |

Non-volatile memory

| Type | Size | User modifiable | Function | Process to delete |
|---------------------------------|-------------------|-----------------|---|------------------------------------|
| WD-S100T2B0A, Solid State Drive | 1 TB + 1 GB Cache | Yes | Main drive for operating system, programs, drivers and data | Remove drive |
| BIOS Chip EEPROM | 32 MB | Yes | BIOS settings, firmware | Factory reset |
| EEPROM chip | 128 Kbit | No | Serial number | Factory only (no sensible data) |
| CAL memory EEPROM chip | 128 Kbit | No | Calibration data | Factory only (no sensible data) |
| EEPROM | 2 Kbit | No | Configuration data | Factory only (no sensible data) |
| FLASH | 16 MB | No | Firmware | Factory only (no sensible data) |

DESCRIPTION OF VOLTAGE SPECIFICATIONS

Input ranges

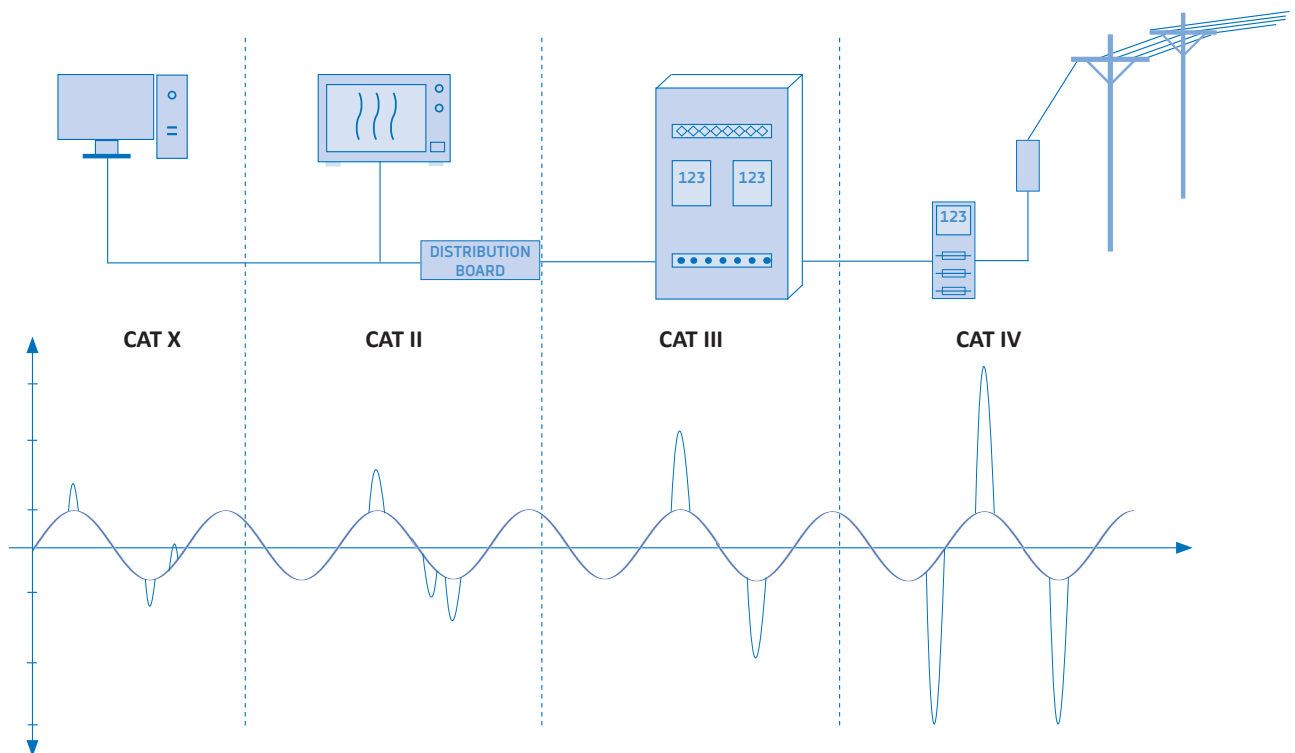
Like all measurement devices DEWETRON measurement equipment provides one or more 'input ranges'. An 'input range' indicates the highest possible value which can be displayed, similar to the limit position of a dial instrument.

Note: The value of the 'input range' does not give any information concerning the allowable scope of application (please refer to rated input according to IEC/EN 61010-2-30).

Rated input according to IEC/EN 61010-2-30

'Rated input' indicates the allowable scope of application of a measurement input according to the IEC/EN 61010-2-30 (Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use - Part 2-030: Particular Requirements for Equipment Having Testing or Measuring Circuits). DEWETRON equipment (respectively measurement inputs) are always specified according to this stated standard, the compliance tests are done by a 3rd party laboratory.

The value 'rated input' specifies the highest possible voltage which can be applied to the measurement input. The IEC/EN 61010-2-30 additionally describes certain measurement categories within a public power grid (see also overvoltage categories IEC/EN 60664-1). Thus, measurement circuits are allowed to be applied according to their specification to the power grid categories as stated below.



The isolation is tested according to the IEC/EN 61010-2-30. The level of the isolation voltage depends on the rated input voltage and on the measurement category. Since potential overvoltage phenomena are higher within higher power grid categories, the isolation voltage needs to be higher too.

DESCRIPTION OF VOLTAGE SPECIFICATIONS

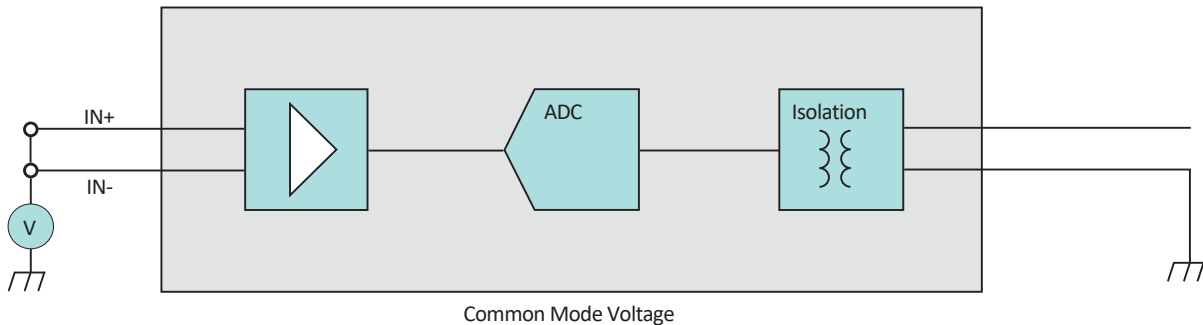
If there is no measurement category specified, the measurement input is not appropriate to be applied to a public power grid.

Examples:

- > **Rated input 600 V CAT II:** The measurement input can be connected to a public power grid within the category II as long as the voltage of the grid does not exceed 600 VRMS. If there is a measurement category specified, the voltage value stated is always considered to be RMS.
- > **Rated Input 600 VRMS:** This measurement input is not intended to be connected to a public power grid. The input would be suitable for measurements within an on-board power system of a train for instance.

Common mode voltage

'Common mode voltage' indicates the highest possible voltage between the two input pins of a channel (e.g. IN+ and IN-) and the reference potential (GND) without clipping the wanted signal.

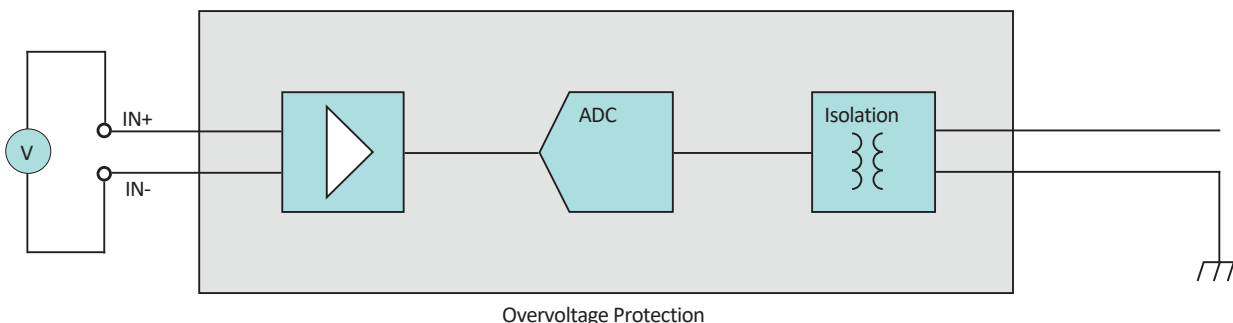


In the very most cases the value of the 'common mode voltage' corresponds to the value of the 'isolation voltage'.

Overvoltage protection

This value indicates the highest possible voltage which will not overload the input protection circuit when applied between two pins of one channel.

Exceeding this value causes the damage of the measurement input in most every case, also other components inside the measurement unit could be affected and it is furthermore a threat to life and physical condition (electric shocks, burn).



DESCRIPTION OF VOLTAGE SPECIFICATIONS

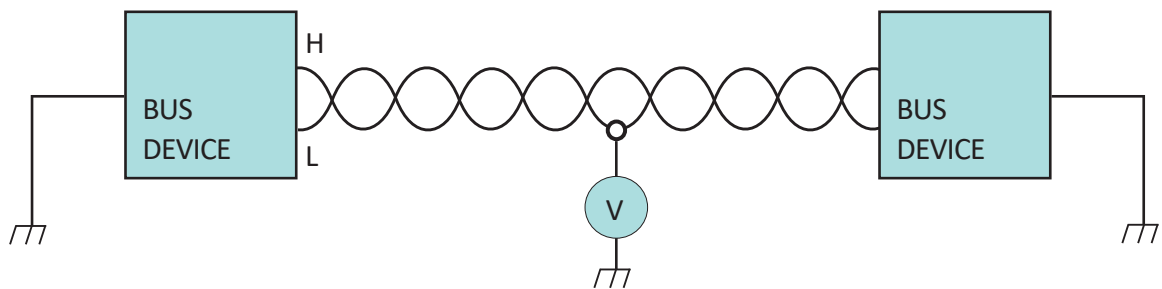
Max. DC voltage @AC coupling

The given value refers to input AC coupled inputs only.

'Max. DC voltage @AC coupling' specifies the highest allowed direct voltage component on the measurement input, when the coupling mode is switched to 'Coupling AC'.

Bus pin fault protection

The specification 'Bus pin fault protection' refers to the wiring of bus systems (e.g. CAN, RS-485, etc.) only. The value indicates the highest voltage which will not destroy the bus input or output when applied between the bus wiring and ground by accident.



▼

DESCRIPTION OF VOLTAGE SPECIFICATIONS

Notes

CE-Certificate of Conformity



Manufacturer:

DEWETRON GmbH

Address:

**Parking 4
8074 Grambach, Austria**

Tel.: +43 316 3070 0

Fax: +43 316 3070 90

e-mail: sales@dewetron.com

http://www.dewetron.com

Name of product:

PU[REC]

Kind of product:

Data recorder

The product meets the regulations of the following EC-directives:

2014/35/EU

"Directive of the European Parliament and of the Council of 26 February 2014 on the harmonisation of the laws of the Member States relating to the making available on the market of electrical equipment designed for use within certain voltage limits"

2014/30/EU

"Directive of the European Parliament and of the Council of 26 February 2014 on the harmonisation of the laws of the Member States relating to electromagnetic compatibility (recast)"

The accordance is proved by the observance of the following standards:

| | | | |
|----------------------------------|------------------|------------------|------------------|
| L V E M C | Safety | IEC 61010-1:2020 | |
| | Emissions | EN 61000-6-4 | EN 55011 Class B |
| | Immunity | EN 61000-6-2 | Group standard |

Graz, November 02, 2020

Place / Date of the CE-marking

Ing. Thomas Propst / Manager Total Quality

▼
NOTES
