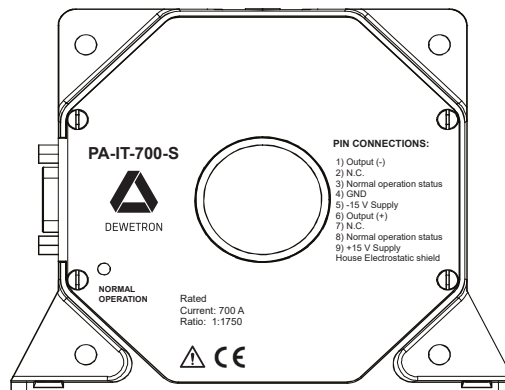


# PA-IT-700-S

## CURRENT TRANSDUCER

FOR ULTRA-HIGH PRECISION MEASUREMENT OF  
CURRENT: DC, AC, PULSED..., WITH GALVANIC  
SEPARATION BETWEEN PRIMARY AND SECONDARY

$$I_{PM} = 700 \text{ A}$$



### FEATURES

- ▶ Closed loop (compensated) current transducer using an extremely accurate zero flux detector
- ▶ Electrostatic shield between primary and secondary circuit
- ▶ 9-pin D-SUB male secondary connector
- ▶ Status signal to indicate the transducer state
- ▶ LED indicator confirms normal operation

### ADVANTAGES

- ▶ Very high accuracy
- ▶ Excellent linearity
- ▶ Extremely low temperature drift
- ▶ Wide frequency bandwidth
- ▶ High immunity to external fields
- ▶ No insertion losses
- ▶ Low noise on output signal
- ▶ Low noise feedback to primary conductor

### APPLICATIONS

- ▶ Feedback element in high performance gradient amplifiers for MRI
- ▶ Feedback element in high-precision, high-stability power supplies
- ▶ Calibration unit
- ▶ Energy measurement
- ▶ Medical equipment

### STANDARDS

- ▶ EN 61000-6-2:2005
- ▶ EN 61000-6-3:2007
- ▶ EN 61010-1:2010

### APPLICATION DOMAINS

- ▶ Industrial
- ▶ Laboratory
- ▶ Medical

## INSULATION COORDINATION

Parameter	Symbol	Unit	Value	Comment
Rated insulation RMS voltage	$U_b$	V	1600	Basic insulation according to IEC 61010-1 – Over voltage CAT III – Pollution degree 2
			300	Reinforced insulation according to IEC 61010-1 – Over voltage CAT III – Pollution degree 2
			1000	Basic insulation according to EN 50178 – Over voltage CAT III – Pollution degree 2
			600	Reinforced insulation according to EN 50178 – Over voltage CAT III – Pollution degree 2
RMS voltage for AC insulation test 50/60 Hz, 1 min	$U_d$	kV	4.6	Between primary and secondary + shield
		$V_{DC}$	200	Between secondary and shield
		$V_{DC}$	500	Between secondary and status output
Impulse withstand voltage 1.2/50 $\mu$ s	$\hat{U}_w$	kV	8.5	-
Clearance (pri.–sec.)	$d_{Cl}$	mm	9	Shortest distance through air
Creepage distance (pri.–sec.)	$d_{Cp}$	mm	9	Shortest path along device body
Comparative tracking index	$CTI$	V	600	-

If an insulated cable is used for the primary circuit, the voltage category could be improved with the following table (for single insulation) (IEC 61010-1 standard):

Cable insulated (primary)	Category
▶ HAR03	▶ 1750 V CAT III
▶ HAR05	▶ 1850 V CAT III
▶ HAR07	▶ 1950 V CAT III

## ENVIRONMENTAL AND MECHANICAL CHARACTERISTICS

Parameter	Symbol	Unit	Min.	Typ.	Max.	Comment
Ambient operating temperature	$T_A$	°C	-10	-	+50	-
Ambient storage temperature	$T_S$	°C	-20	-	+85	-
Relative humidity	$RH$	%	20	-	80	Non condensing
Dimensions	See drawing on page 6					
Mass	$m$	kg	-	0.8	-	-

## ELECTRICAL DATA

At  $T_A = 25\text{ °C}$ ,  $\pm U_C = \pm 15\text{ V}$ , unless otherwise noted.

Parameter	Symbol	Unit	Min.	Typ.	Max.	Comment	
Primary continuous direct current	$I_{PNDC}$	A	-700	-	700	-	
Primary nominal rms current	$I_{PN}$	A	-	-	495	-	
Primary current, measuring range	$I_{PM}$	A	-700	-	700	-	
Measuring resistance, over operating current, temperature and supply voltage range	$R_{IM}$	$\Omega$	0	-	2.5	See graph on page 5	
Secondary current	$I_S$	A	-0.4	-	0.4	-	
Conversion ratio	$K_N$	-	-	1:1750	-	-	
Resistance of secondary winding	$R_S$	$\Omega$	-	20	-	-	
Overload capability <sup>1)</sup>	$\hat{I}_P$	kA	-3.5	-	3.5	@ Pulse of 100 ms	
Supply voltage	$U_C$	V	$\pm 14.25$	$\pm 15$	$\pm 15.75$	-	
Current consumption	$I_C$	mA	-	-	80	Add $I_S$ for total current consumption	
Output rms noise current	$V_{no}$	ppm	0...10 Hz <sup>2)</sup>	-	-	0.05	-
			0...100 Hz <sup>2)</sup>	-	-	0.5	
			0...1 kHz <sup>2)</sup>	-	-	1	
			0...10 kHz <sup>2)</sup>	-	-	3	
			0...50 kHz <sup>2)</sup>	-	-	6	
Re-injected rms noise on primary bus bar	-	$\mu V$	-	-	5	0...50 kHz	
Electrical offset current + self magnetization + effect of earth magnetic field <sup>2)</sup>	$I_{OE}$	ppm	-50	-	50	-	
Temperature coefficient of $I_{OE}$ <sup>2)</sup>	$TCI_{OE}$	ppm/K	-0.5	-	0.5	10...50 °C	
Offset stability <sup>2)</sup>	-	ppm/month	-0.5	-	0.5	-	
Linearity error <sup>2)</sup>	$\epsilon_L$	ppm	-3	-	3	-	
Step response time to 90 % of $I_{PNDC}$	$t_r$	$\mu s$	-	-	1	di/dt of 100 A/ $\mu s$	
di/dt accurately followed	di/dt	A/ $\mu s$	100	-	-	-	
Frequency bandwidth	$BW$	kHz	-	50	-	Small-signal bandwidth, 0.5 % of $I_{PM}$	
				100			

### Notes

1) Single pulse only, not AC. The transducer may require a few seconds to return to normal operation when autoreset system is running.

2) All ppm figures refer to full-scale which corresponds to a secondary nominal RMS current ( $I_S$ ) of 0.4 A.

## OVERLOAD PROTECTION – ELECTRICAL SPECIFICATION – STATUS

The overload occurs when the primary current  $I_p$  exceeds a trip level such that the fluxgate detector becomes completely saturated and, consequently, the transducer will switch from normal operation to overload mode.

This trip level is guaranteed to be greater than 110 % of  $I_{PNDC}$  and its actual value depends on operating conditions such as temperature and measuring resistance.

When this happens, the transducer will automatically begin to sweep in order to lock on the primary current again and the measuring can resume when the primary current returns in the measuring range between  $-I_{PNDC}$  and  $+I_{PNDC}$ .

In overload mode the secondary current generated is a low frequency triangle waveform between -0.4 A and +0.4 A.

Under these conditions:

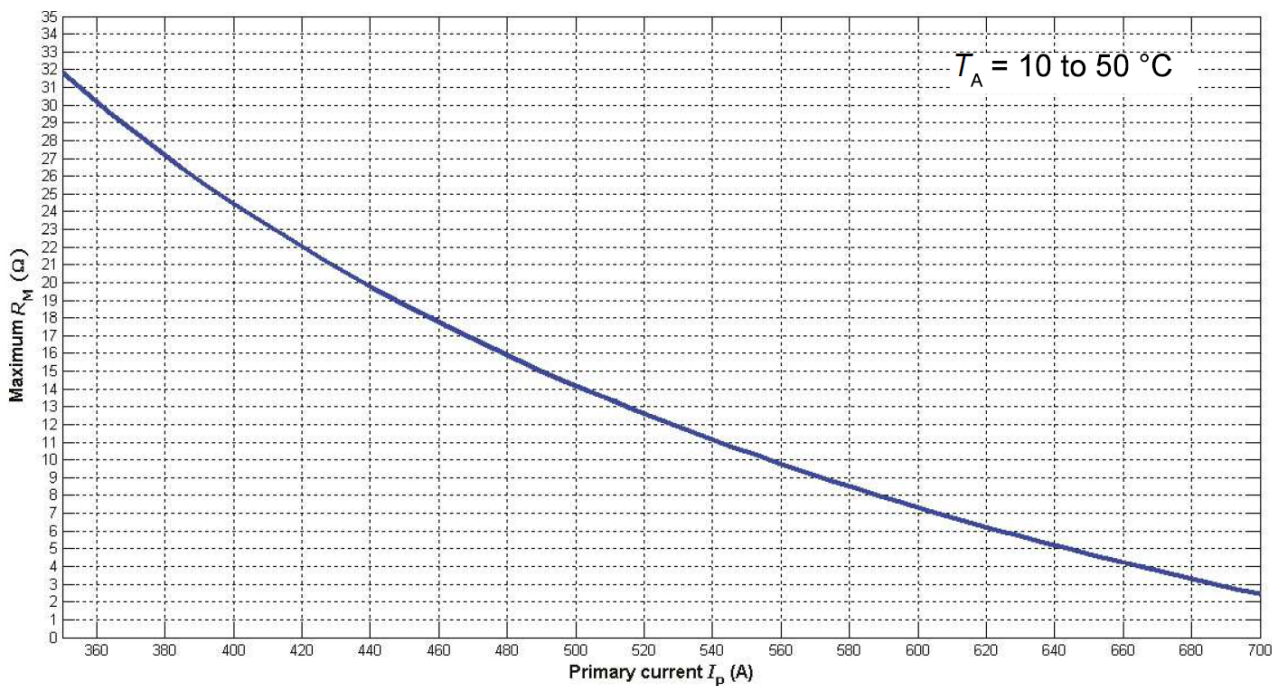
- ▶ The potential-free contact (normal operation status) between pin 3 and 8 of the D-SUB connector switches off, this contact becomes open.
- ▶ The green LED indicator (normal operation status) turns off.

Max. voltage pin 3 and pin 8; off-state	100 V
Max. voltage pin 3 and pin 8; on-state	1000 mA
On-state resistance pin 3 and 8	50 mΩ (typ.)

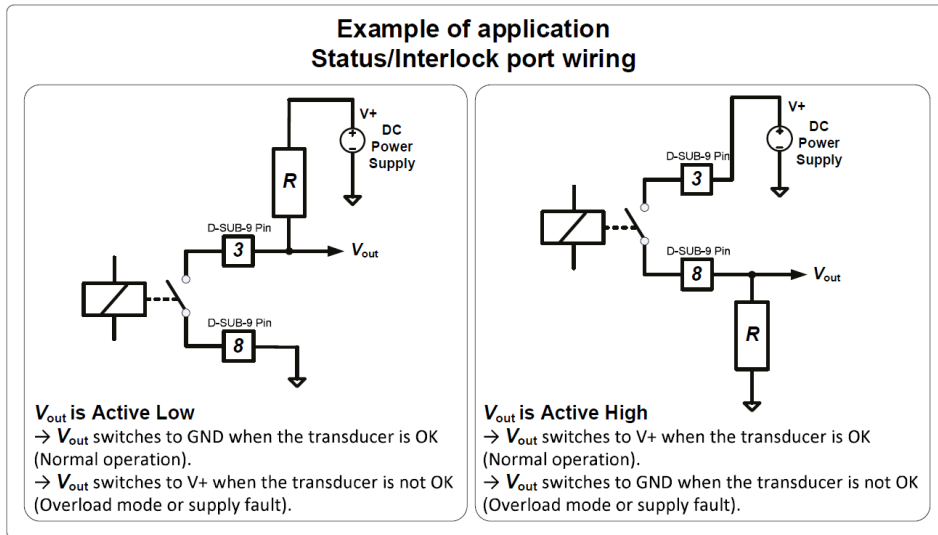
### NOTICE

To ensure a safe recovery from saturation, the maximum burden resistor allowed is 2.5 Ω.

## MAXIMUM MEASURING RESISTOR VS. PRIMARY CURRENT

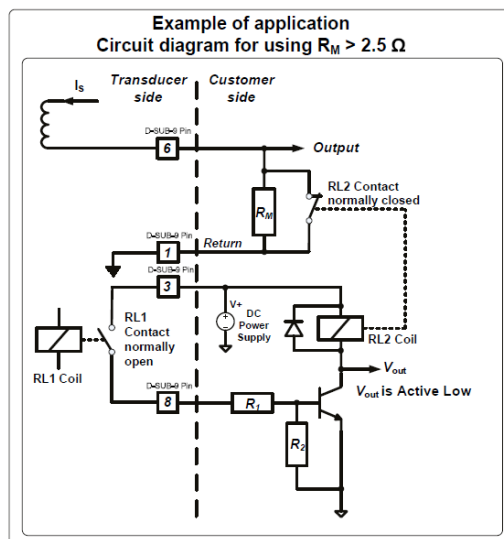


## STATUS/INTERLOCK PORT WIRING



## CIRCUIT DIAGRAM FOR USING $R_M > 2.5 \Omega$

The circuit ensures a safe recovery from saturation when using  $R_M > 2.5 \Omega$ . It allows the transducer to recover normal operation in case  $R_M$  is greater than  $2.5 \Omega$  and an overload is detected by the transducer.



Contact RL 1 (pins 3 and 8)	Contact RL2	V <sub>OUT</sub>	Description
Closed	Open	Low (switches to GND)	The transducer is OK (normal operation).
Open	Closed	High (switches to V+)	The transducer is not OK (overload mode or supply fault).

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## SAFETY

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.

### WARNING



#### Risk of injury

This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.

### CAUTION



#### Risk of injury due to electrical shock

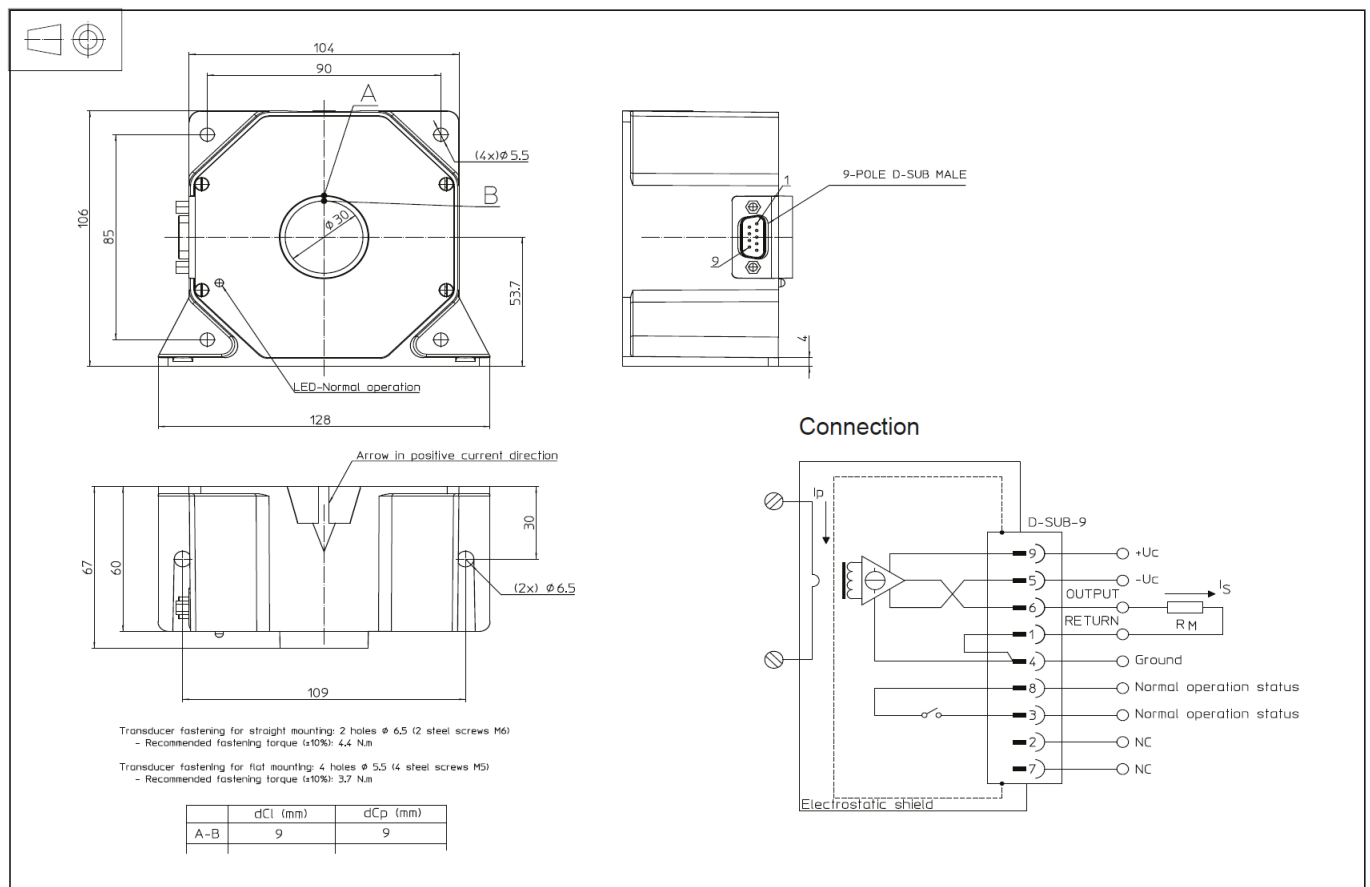
When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary connection, power supply). Ignoring this warning can lead to injury and/or cause serious damage.



This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

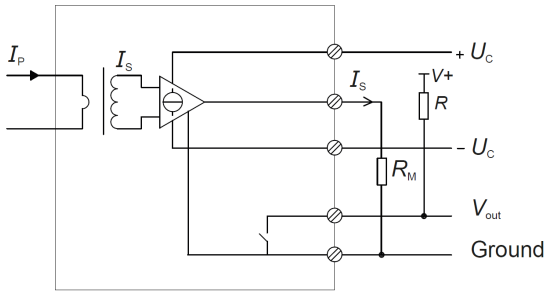
A protective housing or additional shield could be used. Main supply must be able to be disconnected.

## DIMENSIONS



## PERFORMANCE PARAMETERS DEFINITION

The schematic used to measure all electrical parameters is shown below:



### TRANSDUCER SIMPLIFIED MODEL

The static model of the transducer at temperature  $T_A$  is:

$$I_S = K_N \cdot I_P + \text{error}$$

In which

$$\text{error} = I_{OE} \text{ at } 25^\circ\text{C} + I_{OT}(T_A) + \epsilon_L \cdot I_{PM} \cdot K_N$$

Where

$$I_{OT}(T_A) = TCI_{OE} \cdot |T_A - 25^\circ\text{C}| \cdot I_{PM} \cdot K_N$$

$I_S$  : secondary current (A)

$K_N$  : conversion ratio

$I_P$  : primary current (A)

$I_{PM}$  : primary current, measuring range (A)

$T_A$  : ambient operating temperature ( $^\circ\text{C}$ )

$I_{OE}$  : electrical offset current (A)

$I_{OT}$  : temperature variation of  $I_{OE}$  at  $T_A$  (A)

$\epsilon_L$  : linearity error

This is the absolute maximum error. As all errors are independent, a more realistic way to calculate the error would be to use the following formula:

$$\text{error} = \sqrt{\sum (\text{error\_componen})^2}$$

### LINEARITY

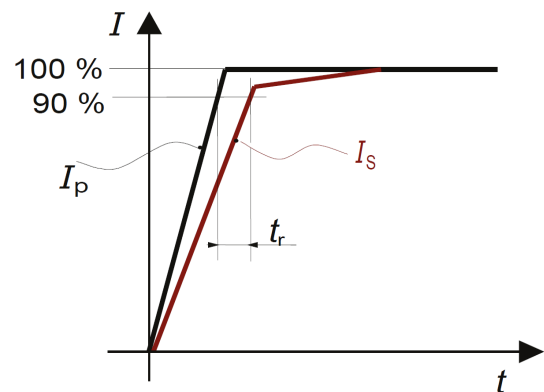
To measure linearity, the primary current (DC) is cycled from 0 to  $I_{PM}$ , then to  $-I_{PM}$  and back to 0 (equally spaced  $I_{PM}/10$  steps). The linearity error  $\epsilon_L$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in parts per million (ppm) of full-scale which corresponds to the maximum measured value.

### ELECTRICAL OFFSET

The electrical offset current  $I_{OE}$  is the residual output current when the input current is zero. The temperature variation  $I_{OT}$  of the electrical offset current  $I_{OE}$  is the variation of the electrical offset from  $25^\circ\text{C}$  to the considered temperature.

### RESPONSE TIME

The response time  $t$  is shown in the next figure. It depends on the primary current  $di/dt$  and it is measured at nominal current.



## CONNECTION

- ▶ Normal operation status (pins 3 and 8)
- ▶ Normal operation means:
  - $\pm 15\text{ V}$  ( $\pm U_c$ ) present
  - zero detector is working
  - compensation current  $\leq 110\%$  of  $I_{PNDC}$
  - green LED indicator is lit

Contact (pins 3 and 8)	Description
Closed	The transducer is OK (normal operation)
Open	The transducer is not OK (overload mode or supply fault)

## REMARKS

- ▶  $I_s$  is positive when  $I_p$  flows in the direction of the arrow.
- ▶ We recommend that a shielded output cable and plug are used to ensure the maximum immunity against electrostatic fields.
- ▶ Pin 4 should be connected to cable and connector shield to maintain lowest output noise.
- ▶ Temperature of the primary conductor should not exceed  $50\text{ }^\circ\text{C}$ .

## MECHANICAL CHARACTERISTICS

- ▶ General tolerance  $\pm 0.3\text{ mm}$
- ▶ Transducer fastening
  - Straight mounting
    - 2 holes  $\varnothing 6.5\text{ mm}$
    - 2x M6 steel screws
    - Recommended fastening torque 4.4 Nm
  - Flat mounting
    - 4 holes  $\varnothing 5.5\text{ mm}$
    - 4x M5 steel screws
    - Recommended fastening torque 3.7 Nm
- ▶ Connection of secondary on D-SUB-9, UNC 4-40 connector
- ▶ All mounting recommendations are given for a standard mounting. Screws with flat and spring washers.
- ▶ Primary through hole  $\varnothing \leq 30\text{ mm}$
- ▶ Installation of the transducer must be done, unless otherwise specified on the datasheet, according to the manufacturer's [Transducer Generic Mounting Rules](#).